



KONGSBERG SEATEX

XPR



XPR Operator & Technical Training

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Long Range Relative Positioning System





XPR Training Course Content

XPR Training

XPR Operator Training

XPR Technical Training



XPR Operator Training

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XPR Introduction

XPR Principles

XPR Product Modules

XPR Operation



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XPR Microwave based DP Reference System

- Features:
 - No maintenance
 - Small size and light weight
 - Easy to install and operate
 - Flexible configuration (100° to 280° coverage)
 - Compatible with Artemis



Front view: XPR Panel



XPR Microwave based DP Reference System

- Features:
 - Easy and quick installation, using existing cabling
 - Operating range from 10m to 5km
 - Automatic target selection (requires Field ID from DP)
 - Operates in all weather conditions
 - Customer replaceable units





XPR Technical Specifications

- Solid state technology (no moving parts)
- Beam forming by antenna arrays
- Frequency range: 9.2-9.3 GHz
- Range accuracy:
- Bearing accuracy:
- Operating range: 10m 5km
- Digital beam:
 - Horizontal beamwidth
 - Vertical beamwidth
- Horizontal opening angle:
- Output rate:

7° 25° 100° pr. panel 1-4Hz

+/- 0.02°

1m



Front view: Antenna elements









Dimensions: 40 x 40 cm, Depth 5 cm, Weight 9kg



Improved Performance with XPR-to-XPR Operations

- Faster target acquisition/lock on target (< 30s on 270° scan)
- Automatic target selection
- Improved false target lock mitigation
- Continuous monitoring in all directions (area of operation)
- Exchange of other data/information between the two vessels
- Improved range and bearing accuracy







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XPR Measuring Principle

to

- Distance/Range:
 - By comparing the signal sent from the XPR on the shuttle tanker to the FPSO with the signal returned from the FPSO the travel time is determined.
 - The distance/Range is then calculated by:

d=distance t₀= start time t₁= stop time c=speed of light

 $-d = \frac{t1-t0}{2} * C$





XPR Measuring Principle

- Bearing calculation is based on:
 - Distance measurement between antenna patch #1 in the interrogator and Tx antenna in the transponder
 - Distance measurement between antenna patch #16 in the interrogator and Tx antenna in the transponder
 - And the known distance between antenna patch #1 and #16





Frequencies & Address Codes

 The XPR operates on frequencies between 9.2 and 9.3 GHz, same as Artemis:

Frequency Pair	0	1	2	3
Interrogator [MHz]	9200	9300	9230	9270
Transponder [MHz]	9230	9270	9200	9300

- In addition to having the correct frequency pair, the selected address code between 0-63 also must be correct.
- The frequency pair and address code is configured in the target list.





- The XPR is fully operational with one XPR sensor on the Shuttle tanker and one on the FPSO.
 - This gives an operational sector of 100°





XPR Flexible Configuration

- Maximum of three sensors can be interfaced to one XPR system
 - Two sensors give an operational sector of 190°
 - Three sensors give an operational sector of 280°
 - Extended number of sensors can be used on both sides to increase the sector

SHT Dual Sensor

shit Triple Sensor

FPSO single sensor

FPSO Single Sensor



Factors Affecting Performance

- The XPR needs free line of sight between the interrogator on the shuttle tanker to the transponder on the FPSO.
- Any object in front of the interrogator might affect the performance of the XPR.
- Flat sea fading.



Factors Affecting Performance

- Flat sea fading
 - Signals reflected from flat sea surface will interfere with the direct signals and signal levels can fade.
 - Lock on target may get lost with wave height less than 0.5m.
 - Sea state, antenna height and distance will influence on this effect





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Main View





Main View







System Status

- Overall status of system.











TR | Active

The system is active and operational. It will search for transponders/targets which are within range. If a transponder/target is within range, the system will display data.

XPR | Reduced

The system is active, but one or more warnings are present. See the Event list for details.

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Target Information

- Signal strength, range and bearing for past 30mins.
- Frequency pair,
 Address code and
 Sensor that are used.

X The Active Frequency pair 0 Address code 8 Sensor 2 FPSO_Seatex 45.4 dB лШ Signal RNG **132**.0_n some and the state of the second 40.0 BNG 004.4 Acceptable value min 20 dB **167**.2° AZM **131.53** m RNG 100.0 Manual Search On - 11 80.0 Sector size [°] Direction [°] 5 ୯ 20 + 0 40.0 20.0 4.35 deg

XPR

Main View





Main View







XPR Main Menu




XPR Main Menu





XPR Main Menu





XPR

Target Selection - 2 Options

Target selected manually by operator

Operator select target from target list

New targets can be added by operator

Target selected automatically by DP

Target is selected on DP and DP sends target selection to XPR

If target is missing in XPR the target is automatically added to the target list



XPR Target Selection





XPR Target Selection

	Select Target				×
	Name 🕶	ld	Freq. pair	Address code	
Manual Mode Target	Balder_1	26	2	14	
Ivialiual ivioue larget	Balder_2	126	2	14	
Selection	C.d. Ilhabela-BOW	220	0	22	
Sciection	C.d. Ilhabela-STERN	221	1	33	
	Caraguatatuba-BOW	240	1	51	
	Caraguatatuba-STERN	241	1	51	
Select wanted target	FPSO_Seatex	24	0	8	
	Gina Krog	244	3	0	
	Jotun_1	37	3	9	
	Jotun_2	137	3	9	
Confirm by clicking OK	OLSA	100	0	10	
	OLSB	1	2	14	
	P-50 Pow	64	2	20	
	P-50 - Stern	65	2	25	
	São Paulo - BOW	210	3	22	
	São Paulo - STERN	211	3	33	
	Asgard A_1	30	2	11	
	Åsgard C_1	5	0	10	
				\sim $-$	
				Cancel OK	



XPR Target Selection





The XPR system have three possible search methods that can be used when the shuttle tanker approaches the FPSO Manual search

Automatic search

GNSS aided search







XPR Search Methods - Automatic Search









AUTO SEARCH





GNSS Aided Search

Requirements

GNSS position input to XPR

True heading input to XPR

Target configured with correct position in target list



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XPR Configuration

XPR Maintenance

XPR Service/Troubleshooting



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Maximum three panel/sensor can be connected to one PU

Each panel/sensor has its own junction box (JB)

Cables are run from the JB to the Remote interface cabinet (RIFC) in a technical room, close to sensor location



XPR



XPR Junction Box



- 1 Blue +
- 2 Black -

Data line to sensor:

- 1 Orange/White
- 2 Orange
- 3 Green/White
- 4 Blue
- 5 Blue/White
- 6 Green
- 7 Brown/White
- 8 Brown





XPR Remote Interface Cabinet (RIFC)

One 24 VDC power supply for each sensor unit installed







XPR

Remote Interface Cabinet (RIFC)

DSL modem for serial line communication to another DSL modem in the Local interface rack (LIR) on the bridge







XPR Processing Unit (Front)





Behind the lid on the left:

- Power switch
- LAN1, network connector, User configurable
- USB port for software upgrades, backup and to copy log files out from the system



XPR Processing Unit (Front)









			-	(R)				(2)				(45)	-		Kongst Made in No	erg Seater	· ((5
					1										9	5	,	
GNSS 1	GNSS 2	IALA	COM 1	COM 9		M 10	COM 11	ALARM	1	MRII		ANALOG OUT				1	1	
			COM 2	COM 12		M 13	COM 14		IMU		PPS	ANALOG OUT	, 1	TP M	mart 1 minute Martinese Martinese Martinese			/
				PIN REF	RS-422 RX A • RX B	RS-232 CTS RX			MRU 1 2	GND ● LGND	6	MRU TX A MRU TX B		W	Input: 100-24 Fuse: 2A, L25 Class1: Must	0 VAC: 2A, 47-6 60. Replace with be connected to	53 Hz h same type and ra o grounded outlet (ating only
USB 2 USB 3	LAN 3 LAN 4	KEYB	VGA	3 4 5	GND TX_A TX_B	GND RTS TX			3 4 5	NC MRU 1PPS_N MRU_1PPS_P	8 9 10	MRU_RX_A MRU_RX_B 24V_MRU			PN: RAD-E	-PUX_00		

LAN 2 – User configurable LAN 3 – User configurable LAN 4 – User configurable

USB 2 & 3 – User configurable

Port		(IP) address
LAN 1	At the front. Reserved for support	192.168.4.55
LAN 2	Sensor units (Local interface rail/DSL modem) optional DSL line or distribution of data	192.168.1.55
LAN 3	Sensor units (Local interface rail/DSL modem)	192.168.2.55
LAN 4	User configurable	192.168.3.55











XPR Bracket for three panels







XPR Three panels installed







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XPR Configuration





XPR Settings Menu





By default, the system is locked for editing

To unlock click on the «lock» symbol

X Settings Display i A Network DP KONGSBERG Output Input XPR Version: 1.2.0.a1 Details Vessel Sensors About Advanced

XPR

Settings Menu



XPR Settings Menu

Type in the password, by using the onscreen keypad or the keyboard

The password is «stx» Note: the password is case sensitive

Settings		×
Display		
Network	Enter password to continue	
DP		
Output	q w e r t y u i o p	
Input	caps a s d f g h j k l : shift z x c v b n m , .	
Vessel		
Sensors	Cancel OK	
About		
•	Advanced	



XPR shows «un-lock», and configuration can be changed

XPR Settings Menu





XPR Settings Menu



Display settings:

- View orientation
- On/off the display of manual search
- On/off the view of the display keypad
- Select measurements units
- On/off remotely controlled palette



XPR Settings Menu



0			
Display	System network and IP settings Processing unit	Sensors	
Network	LAN1		
DP	192 168 4 55		
Output	LAN2		
Input	LAN3		
Vessel	192 168 2 55		
Sensors	LAN4		
About	203555		




Settings

	Dis	splay	DP interface settin	gs		
ottinge	Ne	twork	Telegram	PSYRAD	Artomic ASCII 117	ArtomisADB
ettings:			FOART	FOARAD	ArtemisAoonAT	AItemisADB
be		·	Communication type Serial	UDP/IP		
· · · · · · · · · · ·	Out	itput	Sarial Dart	Cabla ID		
tion type,	Inp	out	COM9		1	
or UDP/IP	Ves	ssel				
0. 021/11						
	Ser	IISOFS				
rking on	Abo	out				
ble /						

DP interface settings:

- Telegram type
- Communication type, either Serial or UDP/IP
- Serial port
- Cable ID, marking on the serial cable

Advanced

X







X Settings Input Display Name Input settings: Network NMEA input #1 Configure automatic DP Telegram Ŧ GGA ZDA THS PSALB DDC Output target selection from Communication type Input UDP/IP **DARPS or DP** Vessel Serial Port Cable ID 1 COM9 A -Sensors About << >> Add Input Delete Input XPR will selects target and enter active/standby mode automatically Advanced

XPR

Settings Menu







		Settings	×
		Display Vessel details	
(Vessel setting:	Network Vessel name Vessel	
	- Name	DP Dimensions	
	Longth and width	Output Length [m] Width [m] 250.0 250.0 250.0	
	- Length and width	Input Fixed heading [1]	
	- On/off fixed heading,	Vessel On III 15	
	if there is no gyro	Sensors	
	input	About	
	Input.		
			Advanced



Soncor cotting:	Settings	_			×
Sensor setting: Enable sensors with IP address and corresponding serial number is displayed Configure bracket placement with yaw angle	Settings	Sensor settings Enabled	Name Sensor1 Sensor2 Sensor3	Address 10.0.80.190 * 10.0.80.191 * 10.0.80.192 * Dist from center [m], positive starboard 0.0	Serial 19-018686 19-018692 Dist from keel [m], positive downwards 0.0
					Advanced







	Settings						×
Details on connected sensors.	Display Network DP Output			KON	GSBERG		
SW Ver. of processing software and graphical user interface. Relevant when calling support for assistance.	Input Vessel Seneore About	Sensor #1 8W version FW version: Seriat:	Sensor #2 SW version HV version: FV version: Seriat:	Version Sensor #3 BW version: HW version: Senat:	XPR n: 1.2.0.a1 Zetails XPR Core SW version: 1.2.0.a1	HMI SW version: 12.0	
							Advanced



After any changes, verify that the XPR is ready for operation.

- System status should show Active
- Time indicator should run





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Maintenance – Backup and Restore

System backup and restore:

- Backup should be made after installation has been completed.
- Backup will include operating system, XPR software and all configured parameters.

Procedure to create backup located in the XPR Installation manual.



XPR Maintenance – Software Update





XPR Maintenance – Software Update

Software update:

- Insert USB stick with new software into USB port in front of the Processing Unit.
- Select SW Update under Tools menu.

Further information will be received together with the new software.

System will restart after update is completed.





Periodic maintenance:

- It is important to keep the Sensor Unit cover clean to get accurate and reliable signal.
- Clean the Sensor Unit cover with a moist anti-static cloth on a regular basis.
- Inspect the Sensor Unit cable and cable gland, replace if necessary.
- Inspect the Sensor Unit screws are properly tightened.
- Check that there is no noticeable corrosion on metallic parts.





Periodic maintenance:

Caution: Make sure power in Remote Interface Cabinet is switched off before opening Junction Box.

- Check that there is no evidence of water and dust
- Check that there is no damage to wires and cables
- Check that terminals are tightened
- Check that the cable glands are properly tightened
- Check that the earthing connections are satisfactory
- Check that the integrity of the conduit system is maintained
- Check that there is no noticeable corrosion on metallic parts





Periodic maintenance:

Inspecting the Remote Interface Cabinet, recommended inspection once a year.

- 1 Check the door hinges for ease of movement.
- 2 Check the door lock for ease of movement.
- 3 Check the gasket in the contact edge area.
- 4 Check all components and surfaces for external damage.
- 5 Check for traces of corrosion.





Periodic maintenance:

Cleaning of Processing Unit air inlet recommended every 6 months depending on the air quality in operation's location. Steps:

- Remove cover.
- Remove the filter and clean it by washing or vacuuming.
- Replace the plastic cover with the cleaned filter.





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Wrong heading of target

If target/remote vessel is shown 180-degree error in display, azimuth setting is wrong.

To change this target parameters must be changed.



Service





XPR Service





X Target Editor ld Freq. pair Address code Name 🔻 Balder_1 A target is selected Balder 2 C.d. Ilhabela-BOW C.d. Ilhabela-STERN Caraguatatuba-BOW Select Edit Caraguatatuba-STERN FPSO_Seatex FPSO_Test Gina I Jotun_1 Jotun_2 Munkholmen OLSB P-50 - Bow P-50 - Stern São Paulo - BOW São Paulo - STERN Åsgard A_1 Åsgard C_1

XPR Service

Delete

Edit

New



\times Edit Target Frequency pair Dist from stern [m] ld Input password to enable 26 2 5.1 target editing. 1-9999 0.3 Positive forward Dist from center [m] Name Address code -6.8 Balder 1 14 Change the Azimuth 1-20 characters Positive starboard reference Length [m] Dist from keel [m] Width [m] Sector Norway 240 40 0 Positive downwards Click on Save. Compatibility Azimuth 0° reference Latitude The target should now 59 11.461699800 Artemis MK5 Aft Ν N/S dd show up correct in the mm.mmmmm Longitude display view Е 2 23.146000200 E/W ddd mm.mmmmm Save Cancel

XPR

Service





Unstable signal from XPR

If experiencing unstable signal, check the signal, range and bearing history

Click in this field to open Target history view





XPR Service







XPR





XPR



Click on desirable interface/Port to view data activity on this interface.

Port Monitor	×
TCPUDPSerialPortrxtx	rxcounttxcountinterfacetypesubtypeportnamebaudratelinestatusparitywordlengthstopbitbufferin044472Telegram out 1 serialRS422ttyhx79600DtrRtsCtsN810bufferoutparityerframingeroverrunid0002655555555
DP IF 0 62216	Received
Telegra 0 44472	
KSRepor 0 40404	
	Sent
	<pre>\$PSXXPR,150244.20,3,132.28,1.0,3.22,0.02,167.11,120*0F \$PSXXPR,150244.45,3,132.34,1.0,3.24,0.02,167.15,119*09 \$PSXXPR,150244.68,3,132.42,1.0,3.33,0.02,167.11,121*0E \$PSXXPR,150244.93,3,132.25,1.0,3.36,0.02,167.09,121*07 \$PSXXPR,150245.19,3,131.89,1.0,3.23,0.02,167.11,120*0D \$PSXXPR,150245.44,3,131.87,1.0,3.24,0.02,167.10,119*07 \$PSXXPR,150245.69,3,132.20,1.0,3.29,0.02,167.09,120*09 \$PSXXPR,150245.94,3,132.46,1.0,3.22,0.02,167.16,119*04 \$PSXXPR,150246.19,3,132.47,1.0,3.18,0.02,167.11,120*07 \$PSXXPR,150246.19,3,132.47,1.0,3.18,0.02,167.11,120*07 \$PSXXPR,150246.45,3,132.39,1.0,3.25,0.02,167.13,120*08</pre>
Freeze	

XPR

Service





End of Training

