

MAN B&W

MOP DESCRIPTION 1008

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50-98ME/ME-C

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1. Important!





Please note that access to the areas of the MOP computer behind the user interface screens shown in the appendix of this manual, is restricted to personnel authorised by MAN Diesel & Turbo.

Altering items in the restricted area of the MOP may result in engine failure.

2. General

The Engine Control System (ECS) consists of a set of controllers, see Plate 70317.

Briefly described, the functions of the controllers are:

- EICU The Engine Interface Control Units handle the interface to external systems.
- ECU The Engine Control Units perform the engine control functions: engine speed, running modes and start sequence.
- ACU The Auxiliary Control Units control the pumps of the hydraulic system unit and the auxiliary blowers.
- CCU The Cylinder Control Units control the ELFI/ELVA and FIVA valves, starting air valves, and the ME cylinder lubricators.
- SCU The Scavenge Control Unit controls both the Exhaust Gas Bypass (both on/off as well as variable bypass) and VT- Variable Turbocharging. (Optional)
- MOP The engineers' interface to the ECS.

Normal Working Sequence

The following is an example of how the control units of the ECS work together during normal operation.

EICU

The EICUs receive navigational inputs from the control stations and select the active station based on signals given by the 'Remote Control' system.

The main navigational command is the speed set point (requested speed and direction of engine rotation).

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In the EICUs the raw speed set point is processed by a series of protective algorithms. These ensure that the speed set point from which the engine is controlled is never harmful to the engine. An example of such an algorithm is the 'Barred speed range'.

Now the processed speed set point and the selected engine running mode request are available via the control network to be used by the ECUs as a reference for the speed control and engine running mode control.

The two redundant EICU units operate in parallel.

ECU

The engine speed control requires that the amount of fuel is calculated for each cylinder firing. The calculation made by the speed controller (ECU) is initiated in relation to the crankshaft position, so that the execution is started just in time to make the fuel injection. This is controlled by the tacho function.

The output from the speed controller is a 'request for fuel amount' to be injected for the next combustion. This request is run through different protective algorithms – the fuel limiters – and the 'resulting amount of fuel command' is produced.

Based on the algorithm of the selected engine running mode, the injection profile is selected, the timing parameters for the fuel injection and exhaust valve are calculated and the pressure set point for the hydraulic power supply derived.

Based on the user input of fuel sulphur content, minimum feed rate etc., the resulting cylinder lubrication feed rate for each individual cylinder unit is calculated.

The resulting amount of fuel command, the requested fuel injection profile, the timing parameters and the resulting cylinder lubrication feed rate amount are all sent to the CCU of the cylinder in question via the control network. Likewise, the hydrulic pressure set point is sent to all ACUs.

For redundancy purposes, the control system comprises two ECUs operating in parallel and performing the same task, one being a hot stand-by for the other. If one of the ECUs fail, the other unit will take over the control without any interruption.

CCU

In appropriate time for the next firing, the CCU ensures that it has received new valid data. Where after the injection profile start angle is set up using the tacho function.

On the correct start angle the injection is initiated and is controlled according to the fuel amount command and the injection profile command.

When the injection is completed, the exhaust open and close angles are set up using the tacho function and the exhaust valve control signal is then activated on the appropriate crank angles.

The cylinder lubricator is activated according to the feed rate amount received from the ECU.

All of the CCUs are identical, and in the event of a failure of the CCU for one cylinder, only this cylinder will automatically be put out of operation. (Running with cylinders out of operation is explained in Chapter 704-04.

ACU

The ACUs control the pressure of the Hydraulic Power Supply system and the electrical start-up pumps using the 'Pressure Set point' given by the ECUs as a reference. Furthermore the start and stop of the auxiliary blowers are controlled according to the scavenge air pressure.

The control of the auxiliary equipment on the engine is normally divided among the ACUs so that, in the event of a failure of one unit, there is sufficient redundancy to permit continuous operation of the engine.

MOP

The Main Operating Panel (MOP) is the main information interface for the engineer operating the engine. The MOP communicates with the controllers of the ECS over the Control Network. However, the running of the engine is not dependent on the MOP, as all the commands from the local control stations are communicated directly to the EICU's/ECS.

The MOP is located in the engine control room. It is a PC with a touch screen as well as a trackball from where the engineer can carry out engine commands, adjust the engine parameters, select the running modes, and observe the status of the control system. A back-up MOP is also placed in the engine control room (*see Section 703-09 for detailed MOP-description*).

Control Stations

During normal operation the engine can be controlled from either the bridge, the engine control room or the Local Operation Panel (LOP).

The LOP control is to be considered as a substitute for the previous Engine Side-Control console mounted directly onto the MC-engine.

The LOP is as standard placed on the engine.

From the LOP, the basic functions are available, such as starting, engine speed control, stopping, reversing, and the most important engine data are displayed.

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To start and run the engine from the LOP, some conditions have to be fulfilled. Next to the LOP, a nameplate (containing the text, highlighted below) is placed. The name plate comprises the conditions that have to be fulfilled before start.

Main Engine Start from Local Operating Panel			
In order to start/stop and operate the main engine from the			
as the active control station. This is normally done via the request / acknowledge facility of the Remote Control System. However, it is possible to override the normal change-over procedure by means of the 'Forced Take Command' push button. Activating this button will force the control to the local control station.			
Before start, the hydraulic oil pressure must be higher than 150 or 205 bar, depending of the hydraulic system is at 200 or 300 bar. After shut down, the pressure has to be rebuild which may take 60 - 120 seconds.			
To stop the engine: Activate STOP (and reset shut down)			
To start the engine: Change from STOP to START			
If the auxiliary blowers are running, the Engine Control System will start the main engine automatically without delay.			

If the auxiliary blowers are stopped, the Engine Control System delays the start until the auxiliary blowers are started and running. Then, the Engine Control System will start the main engine automatically.



1. Main Operation Panel (MOP) (Overview)

The MOP is the Human Machine Interface (HMI), through which the Engine Control System (ECS) and thus the ME engine is operated. The HMI is described in sections 703-14 through 703-18.

The MOP is basically a marine approved and certified PC with 24DC supply and touch screen.

An actual installation comprises of two MOPs where both are placed in the engine control room (ECR). Typically MOP A is placed in a console opposite the manoeuvring handle (the normal operation position) and MOP B on a desk. The two MOPs are operationally fully redundant to each other. Though some of the more advanced troubleshooting facilities are only available on MOP B. Normally only MOP B has a keyboard connected.

1.2.7 Creating Screen Dumps

Creating screen dumps can be carried out on a MOP with an attached keyboard. To create a screen dump go to the screen in question and, press the [Prt Scr] button on the keyboard to capture the screen.

Press Crtl + Esc to gain access to the windows menu and open a program like Wordpad or Paint and press Paste to copy the screen dump into the program.

1.1 Description

MOP A has no keyboard or mouse. Both may optionally be equipped; a trackball typically replaces the mouse.

A keyboard is essentially not required during normal engine operation and a virtual keyboard is displayed in case textual input (e.g. password) is needed.

Instead of traditional use of a mouse, the operator touches the graphic elements on the screen in order to interact with the ECS.

1.2 Service kit

The MOP comes with a service kit. The kit comprises of a CD-ROM drive (if not build-in), a keyboard and a CD with the operating system, and is setup specifically for this PC type.

1.3 Issues to both MOP type

1.3.1 Ethernet connections

Only MOP B may be connected with an Ethernet connection to other systems such as CoCoS-EDS. Special care must be taken when connecting to networks of any kind to avoid virus and worms on the MOP. Connection to other systems is illustrated on plate 70319 fig 1.

1.3.2 Unauthorised software

DISCLAIMER: MAN Diesel disclaim responsibility for any event or condition that originates from installation of unauthorised software. This includes, but is not limited to, virus.

To emphasize the disclamer, yellow stickers are placed at suitable places on the MOPs.



If it is necessary to extract data from a MOP, it is recommended to use the in-build CD-Rom burner, instead of a USB-stick.

1.3.3 Control Network

Each MOP is connected to the ECS by means of the Control Network that interconnects the nodes in the ECS. Control Network is implemented as two independent networks for redundancy as shown on Plate 70332.

1.3.4 Maintenance

Normal PC maintenance tools and cleaning detergents apply.

1.4 Software Scope of Supply

There are three different types of software supplied with the ECS:

- 1.4.1 Operating System
- 1.4.2 Engine Control System
- 1.4.3 Service Parameters

This software is either stored on a set of CD-ROMs or on a pair of USB sticks. In either case it is important that the software is stored in a proper place where it is accessible and can be found on request. The recommended storage place is together with the engine manual.

In case the software is stored on USB sticks these might be equipped with a

Read/Write selector. This switch should normally always be set to Read.

In addition to the above there will also be the following two types of software as a part of the software supply:

1.4.5 CoCoS EDS

1.4.6 PMI software

These last two types of software are not to be installed on the MOPs, but instead on a separate PC (see plate 70319 fig. 1). However having these programs running correctly is essential to achieving optimal performance of the engine and ECS. Both of these programs include user manuals and instructions together with their installation.

1.4.1 Operating System

The Operating System is the software that is used for the MOPs. This is an embedded version of Windows XP. This is normally preinstalled by the MOP supplier and delivered together with the MOP hardware.

1.4.2 Engine Control System

The Engine Control System is a set of applications installed on the MOPs that enable them to perform their main function, i.e. it turns them into the MOPs.

A very important aspect of the Engine Control System is the version (e.g. "1008-4.1" or "0905-8.2"). It is critical that the version of the software stored on USB/ CD-ROMs is the same version that is currently installed. The currently installed version can be seen on the Version Screen on the MOPs (this screen is described in more detail in section 703-18).



Always ensure the version of the installed ECS matches the version of ECS stored onboard.

1.4.3 Service Parameters

The Service Parameters software functions of a backup in case of major system failure. Normally it should not be used as the MOPs automatically store backup versions of the parameters from the MPCs.

1.4.4 Use Cases for Software

The two normal use cases for the software stored onboard are:

- A. The replacement of a MOP (by crew)
- B. Service visit including update of parameters and/or ECS version

For case A (a new MOP) the Operating System will normally be preinstalled, so when the MOP powers up it will seem identical to a standard Windows PC. The task is then to install the Engine Control System.

This is done by inserting the software medium (USB or CD-ROM) into the PC and then locating the correct install script. There will normally be two options: "in-stall_mopA_XPE.bat" and "install_mopB_XPE.bat". These are both placed on the same CD-ROM/USB. It is important to select the script matching the MOP being installed.

After successful completion of the installation (follow the on-screen instructions) the MOP main application can be started using the "Start MOP" option in the Windows Start menu.

After starting this application the MOP will automatically acquire configuration information and parameter backups from the MPCs.

For case B (service visit where parameters and/or ECS version is changed) it is important that the visiting service engineer ensures that the ECS version and service parameters stored onboard are still correct. This either means supplying a new set of CD-ROMs or updating the data on the USB stick (momentarily changing the Read/Write selector to Write).

1.4.5 CoCoS EDS

This software is used for the data logging program that is collecting data from the ECS. It is to be installed on the same PC that is running the PMI software.

Always ensure that this software is running correctly since this will greatly enhance the options regarding troubleshooting and faultfinding available.

Since the CoCoS EDS interfaces to the ECS for data logging it is important to ensure that the versions are compatible. For instance in case of an update of the ECS, make sure that CoCoS EDS is also updated.

The program DatGat is included with the CoCoS EDS software. This program is a valuable tool for extracting data from the ECS for use during troubleshooting. Instructions on how to use DatGat is included with the installation.

1.4.6 PMI Software

The PMI software comes in one of two versions: As minimum an offline version is delivered with the ECS. Alternatively the engine may be equipped with PMI Autotuning. In either case the PMI system is a valuable tool for performance measurements and as a basic for engine adjustments.

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Fig. 1



Fig. 2



Edition 0004

1. HMI (Human Machine Interface)

The HMI consists of four fixed areas always shown. See Plate 70319 Fig. 2 page 15.

- 1. An Alarm Status Bar showing the oldest non-Acknowledged alarm and Alarm status at the top of the screen.
- 2. A Navigation Bar at the right side of the screen.
- 3. A Toolbar at the bottom of the screen.
- 4. A Screen area (rest of the Screen)

The HMI operates with two password levels, which are Operator level and Chief level.

Operator level:

From the Operator level is it not possible to set any parameters. It is for normal operation and monitoring only.

Chief level:

In addition to the Operator level, this user level has privileges to set parameters (setpoints, engine states and engine modes). A password must be supplied in order to access Chief level.

There is no limit in the number of unsuccessful attempts to enter the correct password. The password is hard coded in the system and can therefore not be changed.

2. Alarm System

The alarms on the MOP panel are all related to the Engine Control System.

On plate 70319 fig. 1 is shown the ECS and the possibilities to communicate with the ordinary alarm system, and the safety system. These three systems are able to interact with each other i.e. in case of a slow down and a shut down.

The shut down and slow down can be divided into two kinds – cancellable and non-cancellable.

If a cancellable shut or slow down occur the safety system will release an alarm prewarning and after timeout of the prewarning periode activate the shut/slow down.

If a non-cancellable shut or slow down occur the safety system must release the shut or slow down immediately.

3. Alarm Handling

Alarm handling is carried out from one of the following four screens

- 1.1 Alarm List
- 1.2 Event Log
- 1.3 Manual Cut-Out List
- 1.4 Channel List

These four Alarm Handling screens can be accessed via the secondary navigator by pressing the "Alarms" button in the main navigator. When pressing this button, the latest selected alarm screen will be shown on the screen. If no screen has previously been selected, the "Alarm List" is shown. The screen can then be changed via the secondary navigator.

3.1 Alarm List (See Plate 70320)

The Alarm List contains the central facility of the Alarm Handling, allowing for display, acknowledgement and cut-out of raised alarms. Detailed alarm explanation can be accessed for each of the alarm occurrences.

The alarms are displayed in chronological order, with the latest alarm at the top.

The Alarms might be grouped by the ECS if they are related to the same cause in order to simplify the overview of the alarm list. The group can be expanded by selecting a group and pressing the -/+ button on the toolbar. Not all alarms are grouped.

If there are too many alarms to be displayed at the same time on the screen, the remaining alarms can be accessed by pressing the Page-up/Page-down buttons on the Toolbar.

Alarms presented in the alarmlist can be found in three states:

- 1. Alarm non acknowledged
- 2. Alarm acknowledged
- 3. Normal non acknowledged

An alarm can only appear as one line in the alarm list. An acknowledged alarm going into normal or an alarm in the normal state being acknowledged, is immediately removed from the list.

Acknowledgement of a single alarm or all alarms is allowed on both levels

(operator or chief) from the "Ack"/"All" buttons on the toolbar at the bottom of the screen. (When pressing "Ack"/"All" only the alarms visible on the screen are acknowledged).

To see a detailed alarm explanation, press the relevant alarm line. The alarm line is then surrounded by a thick blue line showing that it has been selected. By pressing the button "Info" on the Toolbar, a window will appear just above the Toolbar. This window contains:

- Description
- Cause
- Effect
- Action

So the engineer is able to start troubleshooting on this particular alarm (The detailed alarm explanation is removed by pressing the same "Info" button).

3.1.1 Alarm Line Fields, Colours and Symbols (See Plate 70320)

Each alarm line is divided into the following fields:

Ack. The acknowledgement status field of non-acknowledged alarms contains an icon toggling between two states, alerting the operator of a non-acknowledged alarm.

The status of the alarm can also be identified by the background colour as well as the graphical identification in the Acknowledgement field on the Screen as shown below.

(!)	Non-Acknowledged alarm in alarm state
(\cdot)	Non-Acknowledged alarm in normal state
R	Transition from Non-acknowledge to acknowl- edge of an alarm in alarm state
\bigcirc	Acknowledged alarm in alarm state
×	Unacknowledged alarm is cut out
(\cdot)	Alarm was previously unacknowledged in nor- mal state. Now the state is not available
(n.a.)	Alarm was previously unacknowledged in alarm state. Now the state is not available
Ζ	Transition from Non-acknowledge to acknowl- edge of an alarm in normal state
\bigcirc	Alarm is acknowledged in normal state, and in the process of being removed from the alarmlist

At the upper right corner of the screen four small icons are shown which are (from left to right):

\bigcirc	Number of non-acknowledged alarms
\bigcirc	Number of active alarms
	Number of Manual Cut-out alarms
	Number of invalidated channels

From the toolbar at the bottom of the Alarm List screen, alarms can be cut-out. This feature is described in details in Section 3.3.

Description. This field contains the alarm text (e.g. »HCU oil leakage«)

Status. This field shows the status of the alarm as one of the following:

- Normal
- Alarm
- Low
- High
- Not available
- Auto cut-out
- Manual cut-out

ID. This field contains a unique alarm identity. (e.g. ECUA_010112). This ID must always be used for reference and reporting.

Time. This field shows the time of the first occurrence of the alarm, no matter the status changes. The time is shown in hours, minutes, seconds and 1/100 sec. (e.g.13:47:02.56)

3.2 Event Log (See Plate 70321)

The event log can be used for viewing the history of events and to support the operator in troubleshooting. Events stay in the log even after they have been acknowledged and are no longer active. Alarms are logged with three events in the Event Log. The events are Alarm, Normal and Acknowledged. There can be up to 1 million events logged in the event log.

The events are stored in a database on the MOP's hard disc with both local and UTC time stamps. If more than 1 million events are logged, the oldest events are

discarded.

Each event (with the most recent event on top) is shown as a single line and each event line is divided into the following fields:

ID Unit Tag. This field contains a unique event identity.

Date. This field contains the date of the event.

Time. This field shows the time of the event. The time is shown in hours, minutes, seconds and 1/100 sec.

Description. This field contains the alarm text (e.g. »HCU oil leakage«).

Status. This field shows either Normal or Alarm.

MCo. Shows whether the alarm is Manual Cut-Out or not.

ACo. Automatic Cut-Out.

Ack. The alarm is acknowledged.

3.2.1 Searching for an event from a specific date and time or by tag number.

This feature can be helpful when extracting information to external parties or when investigating an event.

When scrolling up or down on the Event Log screen is not sufficient, it is possible to search for a specific event by tag number by pressing the button "Unit/Tag Filter". When an alarm occurs, it is given a tag number that is stored together with the alarm event. By writing this number in the dialog box and pressing "Apply" the alarm event is shown on the screen.

Similarly, the button "Time Span Filter" sorting can be selected.

Enter the from/to date and time in the toolbar by using the popped up keyboard. Press "Apply" to execute. Note that the entered time has to be in UTC time. As a result the events, inside the selected timespan to the specified date and time, will be selected and shown on the screen.

From the button "Go to Time/Date", events which took place at/on a specific time/ date can be displayed. Note that the entered time has to be in UTC time.

When a filter is no longer needed, remember to remove it (by pressing the button again), otherwise it might seem like the event log is frozen and does not receive new events.

3.2.2 Exporting the eventlog.

From the toolbar "Export Event Log", displayed when the "Export" button is pressed, it is possible to print a copy of the Event Log or make a back-up Dump used for information to external parties or the engine crew themselves.

Should external parties ask for an Event Log record (for trouble shooting purposes), the Event Log record can be saved on a USB memory stick (or Hard Disc Drive if no USB memory stick is available) as a zip file. Be aware of the risk of using USB-sticks generally.

The file name will be: **EventLog<DateTime>.zip** when the file is **saved** on a USB-memory stick.

(Is the Event Log **dumped** to a USB memory stick (or Hard disc Drive) the file name will be: **EventLogDump<DateTime>.zip**).

In both cases the **DateTime** is the UTC time when the file was saved.

The USB memory stick (containing the zip file) can then be handcarried to the ships mail PC and the zip file mailed to external parties for evaluation.

3.3 Manual Cut-Out List (See Plate 70322)

Manual Cut-Out of alarms may be used, for instance, if the engineer has observed a failure of a sensor that is not detected automatically (see below) or if, for instance, a Tacho pick-up is failing (the engine running on the redundant Tacho system) and is continuously giving an alarm and cannot be replaced immediately.

Alarms are sometimes cutted-out automatically. Automatic cut-out may be used by the system to suppress alarms which are unimportant in specific states, e.g. when a sensor is invalidated by the operator.

The manually cut-out alarms are shown in a separate list, which can be accessed from the navigation bar. The manual cut-out screen is in functionality equivalent to the channel list screen. An alarm can be cut-out manually from the screens Alarm List, Manual cut-out List or Channel list.

All alarm channels that have the status "Manual cut-out" are shown in the manual cut-out screen.

Removing ("Re-activating") an entry from the Manual cut-out list is done by highlighting the alarm(s) involved on the screen and thereafter pressing the button "Reactivate" in the toolbar.

3.4 Channel List (See Plate 70323)

The channel list screen contains status information of all alarm channels within the ECS, no matter the status of the individual alarm channel. As default, the alarm channels are listed in tag-name alphabetic order. From the channel list screen, it is possible to cut out (and re-activate) alarm channels.

1. Engine

Engine operation and adjustment is carried out from one of the following five screens, some of which are divided further into subscreens :

- 1.1 Operation
- 1.2 Status
- 1.3 Process Information
- 1.4 Process Adjustment
- 1.5 Chief Limiters

Screens 1.1, 1.2 and 1.3 are related to engine start-up preparations and daily running, 1.4 and 1.5 are related to engine adjustments.

The operator can access these five operation and adjustment screens via the secondary navigator by pressing the Engine button in the main navigator.

On the screen, the displays which can be activated (i.e. pushed like a button) are shown in 3-D graphic and the inactive displays are in 2-D graphic. Once activated, the display is highlighted with a blue line at the outer circumference

1.1 Operation (See Plate 70324)

Operation is the main screen for control of the engine during voyage.

On this screen, "prepare start" can be performed and "slow turn" can be enabled before start of the engine.

Plate 70324 shows the full screen. In the following, a detailed description of the individual fields will be given.

1.1.1 Main State

The main state field contains 3 status fields indicating the current sub-telegraph command states and the states of the engine.

The background colours on the graphics are specified as:

- Blue = Normal state
- Yellow = Warning state
- Red = Alarm state
- Grey/dimmed = Not in use.

The top field indicates the current sub-telegraph command state, which can be one of the following:

- FWE (Finished With Engine)
- Standby
- At Sea

The middle field indicates the states of the engine:

• (Blank)

(engine is correctly operative or blocked according to the sub-telegraph command)

- Engine not blocked (with yellow background): if top field is FWE, and not all conditions are fulfilled.
- Engine not ready (with yellow background): if top field is Standby or At Sea, and not all conditions are fulfilled.

The cause of the states "Engine not blocked" or "Engine not ready" can be seen in the Status screen, Plate 70325, in the field Start Conditions.

The bottom field indicates, with yellow or red warnings, the following four states :

- (Blank) (engine is ready and increased limiter inactive)
- Increased limiter (yellow) is shown when active, (and engine status is not FWE, and neither Start Blocked or Shut down status is active). Increased limiter is a warning condition.
- Start Blocked (red) is shown when active, (and engine status is not FWE, and Shut down status is not active). Start Blocked is an alarm condition.
- Shut down (red) is shown when active. Shut down is an alarm condition.

1.1.2 Command [RPM]

The command indicator button contains six or eight status fields. Two fields highlighted, indicating the current active control station (Bridge, ECR or LOP) and the actual speed command setting for each of the control stations. The actual selected control station is indicated by dark blue (normal selection) or yellow (take command) see below.

The Bridge Control and ECR stations are parts of the RCS (Remote Control System). Only one control station at a time is active.

The active control station is normally selected via the RCS request acknowledgesystem. However, the selection may be overridden from either the ECR or LOP by the "take command" buttons, which are wired directly to the ECS (Engine Control System) and situated on the control station panels.

If the active control station selection is inconsistent, the ECS keeps the last valid active control station as the active station, until a new valid selection is available

(possibly a "take command").

In the event the "take command" signals from both the ECR and the LOP are selected simultaneously, the LOP has first priority and is selected.

1.1.3 RPM Fine Adjust

By pressing the Command [RPM] button, a RPM Fine Adjust toolbar is displayed. It allows the RPM setpoint to be adjusted in operator level. E.g. if the speed command setpoint is 83.8 RPM, it can be fine adjusted to 84 RPM. Moving the handle will disable the fine adjustment mode.



RPM fine adjustment can only be performed in ECR Command mode.

1.1.4 Running Mode and Governor Mode

The engine running mode and governor mode buttons each contains a status field indicating the current active running and governor modes.

Changing the running mode is done by pressing the running mode button. This brings up a toolbar. On the toolbar, the current running mode is selected.

The running modes are typically *Economy* and *Emission*. However, additional modes (*TC Cut Out* and *Custom*) may be available. If only Economy mode is available, the mode selection is not usable (dimmed).

The governor mode can be either RPM Control, Torque Control or Index Control.

Changing governor mode is done similar to changing running mode.

1.1.5 Governor Mode

The speed controller can be requested to calculate the fuel index according to various methods.

Each method is referred to as a 'Governor Mode', and they represent various tolerances for maintaining the engine speed equal to the set point during load and/or set point variations.

For normal operation the following two modes are available:

• **RPM control:**

'Speed' mode - provides the most rigid speed control, leading to large fuel index variations.

• Torque control:

'Torque' mode – the speed control is dampened when the speed is close to the required speed, providing speed control without large index variations, but allowing larger speed variations.

A third mode exists for test purposes:

• Index control:

'Fixed Fuel Index' Mode – A test mode where the index is kept constant as long as the speed is within a preset range. Only if the speed drifts outside this range, will the speed controller become active and regulate the index.

1.1.6 Pressure Indicators

The pressure indicators consist of a bar graph and a status field.

Both the bar graph and the status field indicate the pressure of the medium.

1.1.7 Auxiliary System Status Indicators

The system status indicators display information of the operation mode of the auxiliary systems controlled by the ME ECS. These are all indicators and do not allow changing mode or status. Possible control is made on the screens for the actual systems. Indicators are:

- HPS (Hydraulic Power Supply): Manual, Auto
- Lubricator: Running Stopped, Prelube, LCD (Load Change Dependent) On
- PTO (Power Take Out): Off, Allowed Request, Request (with yellow and warning if a parameter for switching on the PTO is not fulfilled) and Permission.
 - Optional, only if the engine has PTO.
- Auxiliary Blowers represented by two status fields, one indicates the operation mode, which can be Auto or Manual. The other indicates the current status of the blowers, which can be Stopped, Starting, Running or Failed.
- Var.XBP (Variable Exhaust Gas Bypass): percentage open. Optional, only if XBP is installed.
- On/Off XBP (Exhaust Gas Bypass): Open or Closed. Optional, only if XBP is installed.
- VT (See separate manual for Variable Turbocharging System)

Optional, only if VT is installed.

• WHR (Waste Heat Recovery) : Off, Allowed, Request, Request (with yellow and warning) and Permission. The WHR Is ready for use when »Al lowed« is shown(see Plate 70324).

Optional, only if WHR is installed

1.1.8 Start Status Indicator

The start status indicator consists of a single display, showing information on the status of a start attempt.

The status shown can be one of the following:

- · Stopped
- · Running
- · Repeated Start (yellow)
- · Slow Turn Failed (red)
- · Start Failed (red)

1.1.9 Speed [RPM]

The speed indicator consists of a bar graph.

The set point and the actual running speed of the engine are shown in the two displays above the graph.

The uppermost display is the speed command modifier. The speed modifier is a function that may override the actual speed command and control the speed system set point for the engine speed. When the function is active, the control mode is shown in the Speed Indicator.

The available modifiers are:

Stabilizing	The stabilizing modifier defines a speed set point that ensures the starting of the engine.
Stop	The stopped modifier sets the speed set point to zero.
Minimum Speed	The minimum speed command modifier defines a minimum speed set point during operation of the engine.
Maximum Speed	The maximum speed command modifier defines a maximum speed set point during operation of the engine.
Fixed Speed Set	Fixed speed set is activated when running in pitch backup mode from bridge (option for CPP systems).
Shut Down	The shut down modifier sets the speed set point to zero.
Slow Down	The slow down modifier sets the speed set point to a predetermined slow down level.
РТО	The speed is kept higher than ordered to keep the shaft generator connected during start up of the auxiliary engines.
Speed Ramp	Increase of speed is limited by the ramp.
Load Program	The load control makes it possible to load the engine gradually during a predefined time period.
Barred Speed *) range	Indicates that the modifier has changed the pre- set from inside a barred range to either above or below barred range limit. The engine may have 0-2 barred speed range(s).
RPM Fine Adjust	The speed is being modified according to the setting entered in the RPM Fine Adjustment tool- bar on the Operation Screen.
Run Up/Down Prog.	When the chief increases or decreases the speed set significantly, the engine speed follows prede- fined curves. Optional.
Chief Max Speed	If the user is at Chief level, it is possible to define a Maximum Engine Speed on the Chief Limiter screen. See section 1.5.
TC Cut Out	If the TC Cut Out option is installed, the speed will be limited, when the engine is running in TC Cut Out Mode.
WHR	The speed is kept higher than ordered to keep the shaft generator connected during start up of the auxiliary engines.

* Barred Speed Range

If the function is used, the barred speed range(s) is marked on the side of the bar graph. Most engines have two barred ranges and the ranges are identical in the ahead and astern directions (FPP systems). When operating from ECR and Bridge, the speed set is automatically kept outside these range(s).

1.1.10 Pitch Indicator

The pitch indicator is only shown on ships with CPP systems.(see Plate 70324 page 5(5))

The pitch indicator consists of a label and a bar graph, indicating the current pitch setting. The label uses + (plus) or – (minus) to indicate positive (forward) or negative (backwards) pitch. The bar graph is centred at 0 and positive and negative is up and down, respectively.

The pitch indicator bar graph uses a pointed graph to underline the direction (sign) of the current pitch.

1.1.11 Fuel Index Indicator [%]

The fuel index indicator consists of a bar graph and a set of status fields. The top status field indicates the current effective or nearest limiter. The electronic governor will limit the fuel index command according to the actual engine operating conditions. If no limiter is currently active the nearest limiter is displayed on a light blue background. When a limiter is active it is displayed on a dark blue background. Available limiters are:

Start	The start limiter defines a fixed amount of fuel to be used for the first injections during start.
Chief	The chief limiter defines a maximum amount of fuel to be injected according to the settings done by the operator at the screen Chief Limiters.
Scavenge Air Pressure	The scavenge air pressure limiter defines a maxi- mum amount of fuel to be injected based on the actual scavenge air pressure, in order not to overfuel the engine.
Torque	The torque limiter defines a maximum amount of fuel to be injected according to actual engine speed. This is to ensure that the engine torque does not ex- ceed recommended levels.
Hydraulic Power Supply	The hydraulic power supply pressure limiter defines a maximum amount of fuel oil to be injected accord- ing to actual hydraulic power supply requirements, in order to ensure that the hydraulic pressure does not drop below a minimum operation limit.
TC Cut Out	If the TC Cut Out option is installed, the fuel index will be limited, when the engine is running in TC Cut Out Mode

Below the limiter status field is a set of dynamic labels displaying the actual fuel index and the current fuel index limit.

1.1.12 Prepare Start Button

The prepare start function is normally to be activated before start if the engine has been stopped for some time. Pressing the button will start the cylinder pre-lubrication and the auxiliary blowers (if stopped).

When pressed, the button will stay down until the procedure is completed. If the engine has not been started within a certain time, the auxiliary blowers will automatically stop.

The command is available only when the engine is stopped and the prepare startprocedure is not running.

1.1.13 Slow Turn Button

Manual slow turn is used during preparations before start of the engine, and is normally to be used with the indicator cooks open. Slow turn is used for visual inspection of the blow out. When the button is selected, the engine is operated on starting air through the slow turn valve as long as the control handle is activated. If a manual prepared start has not been executed, the system will automatically perform one.

1.1.14 Auto Button

The auto button is pressed when start preparations are completed, and the engine has to be started. When selected the engine will perform a normal automatic start.

If a manual prepared start has not been executed, the system will automatically perform one.

1.1.15 Air Run Button

The air run button function is only available in Chief level.

The air run button can be used in the following situations:

When checking the Tacho system (test), starting air valve test and after maintenance (and after check with the turning gear) to check the function and movement.

Air run function is similar to the slow turning, except that the main starting valve is open and the engine is running faster (still without fuel injection).

Slow Turn and Air Run are activated when the handle is in "run" position. This will rotate the engine until the handle is set to »stop« (or the engine is started by pressing the Auto button).

1.2 Status (See Plate 70325)

The engine status screen provides extended engine information specifically for use when changing the status of the engine, i.e. in the process from FWE to standby state or vice versa.

1.2.1 Main State Field

The main state field shows exactly the same information as the main state field in the operation screen view, Plate 70324. For detailed explanation, see 1.1.1 Main State Field, page 1 in this chapter.

1.2.2 Start Conditions

The Start Conditions field is a status list, showing if the engine is in the intended state (FWE or st.by/at sea). The conditions shown in bold must be fullfilled before the intended state can be obtained.

If a condition is shown with a green check mark, the condition is in accordance with the intended state.

If a condition is shown with a red background and a white exclamation mark the engine is not ready for starting.

If the condition is not relevant the background is dimmed, but a check mark or exclamation mark will still indicate the status of the condition.

The possible status indications of each field are listed below:

- Main Starting Valve in service position (Standby or At Sea) Yellow, when main starting valve is not in service position. Green, when main starting valve is in service position.
- Main Starting Valve Blocked (FWE) Yellow, when main starting valve is not blocked. Green, when main starting valve is blocked.
- Starting Air Distribution System in service (Standby or At Sea) Red, when Starting Air Distribution system is blocked. Yellow, when Starting Air Distribution system is not in service. Green, when Starting Air Distribution system is in service.
- Starting Air Distribution System blocked (FWE) Yellow, when Start Air Distribution system is not blocked. Green, when Start Air Distribution system is blocked.
- Starting Air Pressure (Standby or At Sea) Red, when starting air pressure is below level for bridge start. Green, when OK.
- Control Air Pressure (Standby or At Sea) Red, when control air is vented. Yellow, when control air pressure is low. Green, when control air pressure is OK.
- Control Air vented (FWE) Yellow, when control air is not vented. Green, when control air is vented.
- Turning Gear disengaged (Standby or At Sea) Red, when turning gear is not disengaged. Green, when turning gear is disengaged.
- Auxiliary Blowers (Standby or At Sea) Red, when blowers are not operational. Green, when blowers are operational.

- Hydraulic Power Supply (Standby or At Sea) (Start-up pumps) Yellow, when HPS is not OK. (e.g. in manual mode) Green, when HPS is OK.
- Hydraulic Pressure (Standby or At Sea) Red, if pressure is too low. Green, if pressure is OK.
- Zero Pitch before starting (Standby or At Sea) (CPP systems only) Red, if pitch is not zero before starting. Green, if pitch is zero before starting.

1.2.3 Start Air

The starting air pressure indicator displays the system starting air pressure continuously.

1.2.4 Turning Gear

The field shows either Engaged or Disengaged.

1.2.5 Control Air Pressure

The control air pressure indicator displays the system control air pressure continuously.

1.2.6 Blowers

Shows the status of the auxiliary blowers, which is either:

- Stopped
- Running
- Starting
- Failed

1.2.7 Hydraulic Oil

The hydraulic oil pressure indicator displays the system hydraulic oil pressure continuously.

1.2.8 Crankshaft

Shows the current position of the crankshaft when turning the engine (for maintenance purposes) with the turning gear, and allows checking of the position in case of malfunction of starting air valves. 1.2.9 Pitch Start Blocking Indicator (CPP systems only)

On the pitch start blocking indicator, it is possible to cancel the start blocking. (This could be relevant if the engine is stopped with the pitch in ahead or astern position, and return to zero is not possible due to some failure).

Cancel of start blocking can only be performed from Chief Level. When blocking is cancelled this is shown with the text "Blocking Cancelled" on a red background.

1.2.10 Start Status Indicator

The start status indicator consists of a single field containing information on the current start status.

Three successive start attempt failures or a slow turn failure will cause Start – Blocked. The below conditions are indicated in the start status indicator:

- Stopped
- Running
- Repeated Start (warning)
- Slow Turn Failed (alarm)
- Start Failed (alarm)

1.2.11 Details

Pressing this button will display the individual readings of the Start Air, Control Air and Crank Shaft sensors.

1.2.12 Pneumatic Diagram

In addition to the information described above the screen contains a simplified diagram of the pneumatic starting and control air system. The diagram is intended to indicate the functionality of the system. For a specific engine, further details can be found in the plant installation drawings supplied by the engine builder.

The pilot valves A, B and Slow Turning, can and must be activated to test that the main starting valve and the slow turning valve open and the tightness of the starting air valves in the cylinders. (This test is to be performed regularly with stopped engine, see Chapter 702-01 in the operation manual).

Pressing the field, encircling the pilot valves, opens a tool bar from which activation of the pilot valves is possible.

1.3 Process Information (See Plate 70326)

This screen gives the user a quick overview of the possible limiters/governors used. The screen always shows the values currently in use.

It is important to realise that the values on a light blue background (e.g. Pcomp/ Pscav ratio or Estimated Engine Load) are set points or estimates, whereas those on a dark blue background (e.g. Speed Actual or Hyd. Oil Actual) are actual measurements. Due to the inherent difficulties of estimating process values there will often be some deviations between the set points and the values that can be measured using e.g. PMI equipment.

1.3.1 Running Mode

This field is the same as described in 1.1.4 Running Mode and Governor Mode Field.

An engine running mode is based on an algorithm which continuously determines the fuel injection and exhaust parameters that influence the cylinder process. By controlling the cylinder process (maximum cylinder pressure, compression ratio and blow back), fuel efficiency and emissions can be controlled to a certain extent.

For the ME engine, several running modes may exist. These contain different algorithms, and provide various fuel efficiency and emission characteristics. The running modes are commissioned during test bed running.

1.3.2 Speed Control

This field is the same list of speed modifiers described in Section 1.1.9 Speed Indicator.

The Index Limiter field is the same list of index limiters described in Section 1.1.11 Fuel Index Indicator.

1.4 Process Adjustment (See Plate 70327)

ECS offers two methods for adjustment of the combustion process:

- Auto Tuning for easy tuning of the cylinder pressures for best engine performance
- Manual adjustment of process offsets for cylinder pressures and FO quality

Auto-tuning is described in section 1.4.1. For detailed information and use of auto-tuning is referred to the "PMI Auto-tuning, Operation, User's Reference Guide", included in the PMI installation.



Auto-tuning functions are available only for engines for which the PMI Auto-tuning option has been selected.

Manual adjustment of process offsets is described in section 1.4.2 and is intended for engines equipped with PMI Offline or for adjusting cylinder pressures during operating conditions that do not allow for auto-tuning.

1.4.1 Auto Tuning (optional)

Auto-tuning reduces the workload required for operating the engine continuously at the design conditions, according to the actual running mode and engine load ordered by ME-ECS. Auto-tuning covers adjustment of maximum, compression and mean indicated pressures and is made available as "*continuous auto-tuning*" (fully automatic) and as "*user-controlled auto-tuning*" (each auto-adjustment session commanded by the operator).

Auto-tuning Status

With following conditions fulfilled:

- **Index is stable:** Engine is in steady state operation, indicated by a stable governor index
- Index is sufficient: Index is above minimum required level (app. 25% load, can be plant dependent)
- **Sensor values:** Valid sensor values are available from the PMI auto-tuning system and deviation between cylinders as well as towards the reference are not too large

The functions for auto-tuning are available, informed in the status bar as "Tuning allowed" (green).

If one or more conditions are not met, the status bar will display "Tuning not available", and indicate the reason here fore (yellow or red).
Continuous Auto-tuning

With continuous auto-tuning selected by the operator, the mean pressure level of Pmax will automatically be adjusted in order to minimise the deviation between ordered and measured mean Pmax. The continuous function is only active if the above conditions are fulfilled and will adjust only within narrower limits than available to manual adjustment. The adjustment offsets applied by the continuous function are displayed in the lower right corner of the "Mean" field.

User-controlled Auto-tuning

The cylinder pressures are automatically adjusted once, each time the operator presses the command button in the toolbar. This is available for adjusting either the engine balance or the mean pressure level:

Balancing

By pressing the "Deviation" field ... The operator can command an auto-balancing, that will balance the engine in respect to one or all of the key parameters Pmax, Pcomp or Pi.

Mean Deviation

The operator can command an auto-mean deviation adjustment. The result will be a minimised deviation between the ordered and the actual mean pressure. This function should be used when de viation is larger than allowed to be adjusted automatically by the continuous auto-tuning function.



The user-controlled mean deviation function is intended only for adjustments in relation to fuel property changes, and only when engine is running above Pmax Break Point. Executed at lower loads, it is required for safe engine operation to check the maximum pressures and re-adjust if necessary when engine load is increased.

Applying an offset in Pmax at low load (<BP), may lead to too high Pmax at high engine loads.

1.4.2 Manual adjustment of process offsets

The cylinder pressures can be adjusted by manually setting the corresponding process offsets for control of fuel injection timing and exhaust valve closing time

Cylinder load

From the "Cylinder load" tab, the operator can adjust the load limit on any cylinder, adjust the load balance as well as cut out one or more cylinder units, however only at Chief level. Before taking a cylinder out of operation the restriction in section 704-04 in the Operation Manual must be taken into consideration.

Cylinder pressure

From the "Cylinder pressure" tab, the operator can manually adjust Pmax level and balance, Pcomp-Pscav ratio and exhaust valve open timing.



The "PMax offset all" function is intended used when engine is running above Pmax Break Point. Executed at lower loads, it is required for safe engine operation to check the maximum pressures and re-adjust if necessary when engine load is increased.



Applying an offset in Pmax at low load (<BP), may lead to too high Pmax at high engine load

1.4.3 Fuel Quality

On this screen a function for in- or decreased fuel oil index for all cylinders (FQA = Fuel Quality Adjustment) is available, e.g. in case of changed fuel quality. The specific calorific value and fuel oil density must be checked in the actual fuel oil specification delivered with the fuel samples at bunkering.

When entering new bunker values the ME system will suggest a new value for Fuel Quality Offset. The 'Suggested Fuel Quality Offset' does not influence the engine in any way. In order to change the actual running conditions it is necessary to change the 'Applied Fuel Quality Offset'.

Adjusting the 'Applied Fuel Quality Offset' is required in order to make sure that the internally calculated ME-ECS load (as displayed on the process information screen, see Plate 70326) corresponds to actual engine load (as estimated by e.g. PMI equipment).

Ensuring this match in internal and external power estimation is an important aspect of getting correct functioning of the ME system.

The 'Suggested Fuel Quality Offset' is a good starting point for finding the correct 'Applied Fuel Quality Offset' however the final value must be found in an iterative process where internal load estimation and external load estimation are compared and 'Applied Fuel Quality Offset' is adjusted.

NOTE

Mismatch between internal and external load estimation can give rise to a wide range of problems. Including, but not limited to, too restrictive fuel index limiters, wrong cylinder pressures and wrong CLO usage.

1.5 Chief Limiters (See Plate 70328)

This screen gives the engineer the opportunity to set the following parameters:

- 1. Maximum Engine Speed.
- 2. Manual limitation of index at all cylinders.
- 3. Cut Out of one or more cylinders.

Additionally the states of all HCU can be seen, and it is possible to reset HCU related failure if needed.

In Chief Index Limit [%] press the cylinder bar graph involved. A toolbar at the bottom of the screen allows the operator to limit fuel injection on the chosen cylinder. When the cylinder is to be reenabled, the bar graph of the cylinder involved is pressed and the fuel injection is raised using the arrows on the toolbar followed by pressing "Apply".

1. Auxiliaries

The Hydraulic System, Scavenge Air and Cylinder Lubrication are monitored in the Auxiliaries main navigator.

From each menu, the operator can control and monitor these systems.

The screens are:

- 1.1 Hydraulic System
- 1.2 Scavenge Air, also including WHR, VT and Exhaust Gas by-pass if these are installed.
- 1.3 Cylinder Lubrication

1.1 Hydraulic System (See Plate 70329)

This screen shows a simple schematic drawing of the HPS (Hydraulic Power Supply). The screen shows from three to five engine-driven pumps (depending on engine layout) and two electrically driven start-up pumps. A bypass valve from pump pressure side to suction side is also shown.

EL-HPS: On some plants the main HPS pumps are not engine-driven but instead electrically driven (EL-HPS). In this case there will be no start-up pumps or by-pass valve. Apart from that the following description is valid also for EL-HPS, just ignore the word 'engine-driven'.

If, for some reason, control signal to an engine-driven pump is lost, the pump swash plate is deflected to 100% in ahead direction. Thereby ensuring adequate hydraulic power for running ahead.



On engines with 4 or 5 engine-driven pumps, pump 4 is controlled from ECUA and pump 5 is controlled from ECUB (see plate 70317)

The following buttons can also be activated directly from the screen in Chief level:

- HPS Mode
- Pump Torque Limiter
- Set Point
- Bypass

1.1.1 HPS Mode

Pressing the HPS Mode button activates a toolbar at the bottom of the screen. At Chief level, it is possible to switch between Auto and Manual mode.

In Auto mode it is possible to perform the following commands (both Operator and Chief level)

- 1. Select one of the electrically driven pumps as master.
- 2. Select one of the engine-driven pumps as pressure controlling pump.

In Manual mode (Chief level) the additional command features are:

- 1. Adjustment of the current hydraulic pressure set point (see Section 1.1.3 in this Chapter).
- 2. Operate engine-driven pumps bypass valve using either ACU1 or ACU3 (Bypass valve to be tested for movement every 6 months, at stopped engine, see 1.1.5 in this Chapter).
- 3. Start/stop of the electric start-up pumps.

1.1.2 Pump Torque Limiter

In this field, it is possible to cancel the Pump Torque Limiter. (Chief-Level)

The torque limiter has two functions:

- 1. The total torque to the engine-driven pumps must not exceed a level that can harm gear and chain. Hence, to protect gear and chain, the sum of the swash plate positions must not exceed a predefined value. (Engine specific).
- 2. To protect the individual pumps from breakdown or damage.

By pressing the Pump Torque Limiter field, a toolbar will appear, where the limiter can be either activated or cancelled. (Cancellation of the limiter will raise an alarm on the MOP).

When the limiter is cancelled, the electrically controlled swash plates in the pumps are allowed to deflect to the mechanical limitation, if the need is there. (When the limiter is active, they are only allowed to deflect to an electrically controlled maximum position).

1.1.3 Set Point and Hyd. Oil

Adjustment of the oil pressure set point can be done from the Set Point display, where the actual set point is always shown. The engine must be running. The actual oil pressure is shown at the display as Hyd.Oil.



Adjustment of the Set Point (Chief level and manual mode) is only intended as an option in test or failure situations. As default, the normal operating pressure is in the 200-300 bar range and is set at commissioning. The engine shutdown level is approximately 140 - 180 bars, also set at engine commissioning. Both the operating pressure and the shutdown pressure is engine dependent.

The pressure set point is only relevant for the engine-driven swash plate pumps, as the pressure of the start-up pumps is limited via mechanical adjusted pressure limiting valves. The start-up pumps are automatically stopped or startet as needed.

1.1.4 Double Pipe (Engine dependent)

This display shows the pressure in the outer pipes of the high pressure double pipes. Normally, this pressure should be in the 0-10 bar range, depending on the specific engine layout. See section 708-08 in the operation manual for more details of the hydraulic system.

1.1.5 Bypass Valve

On the main pressure line from the engine-driven pumps, a bypass valve is installed.

At normal running with HPS mode in "Auto", the bypass will open in the event of shutdown of the engine (wind milling can occur). This ensures oil return to the suction side of the pumps and thereby avoids cavitation and unintended wear on the pump parts.

Also, if the shutdown is due to a leakage at the high pressure side, and the engine keeps turning due to wind milling, the amount of oil spilled can be reduced by leading the oil back to the suction side.

By checking the valve manually, it is ensured that the valve is working properly. (The valve is to be checked manually every 6 months.) See chapter 702-01 in the operation manual.

The bypass valve is tested at engine still stand, in Chief level and the HPS mode in manual. For redundancy reasons the bypass valve is controlled both via ACU1 and ACU3.

1.2 Scavenge Air (See Plate 70330)

The scavenge air screen contains information and controls for monitoring and operating the auxiliary blowers, exhaust gas bypass and VT System. (engine dependent).

By pressing the "Details" button, indication of the current scavenge air pressure is shown for each individual scavenge air sensor.

The blowers are normally operating in Auto mode. Operating conditions are:

The blowers are started when :

- "prepare start" button is pressed (Operation Screen)
- manoeuvring handle is moved to start position, prompting the system to perform an automatic prepare start (engine start is delayed until blowers are running and pressure is correct)
- engine is running but the scavenge air pressure is below a certain value (e.g. during manoeuvring)

The blowers are stopped when

- engine is shut down
- the current sub-telegraph command state is moved to FWE position
- 10 minutes after engine has been stopped (adjustable)
- engine is running and the scavenge air pressure is above a specified level
- After prepare start if no start has occured within the pre-determined time

If a switch to manual operation is required, this is done by pressing the "Blowers Mode" push button (see Plate 70330). By pressing the individual blower 3D display at chief level and manual mode, it is possible to start or stop the individual blower.

The screen contains 2 to 5 blowers, depending on the engine layout. The state of each blower is shown. Status is either stopped, starting, running or failed.



Manual operation of the blower is mainly intended for use during fault-finding and test situations. Selecting Manual Mode will therefore also raise an alarm on the MOP.

1.3 Exhaust Gas Bypass and VT System (engine dependent)

Monitoring of the Exhaust Gas Bypass Systems and VT System is performed from the Scavenge Air screen.

The actual positions and settings of the on/off bypass, the variable controlled bypass valves and VT System are always shown on the screen.

By pressing the "Bypass Mode" push button (chief level), the bypass valve modes can be changed between automatic and manual.

In manual mode (chief level), the variable controlled bypass valve can be opened/ closed or set to the angle desired.

In manual mode (chief level), the on/off bypass can be opened or closed.

For a detailed description of the VT System and Exhaust Bypass System see separate manuals.

1.4 Cylinder Lubricators (see Plate 70331) ME Lube

The ME lube Control System provides the operational monitoring and control of the ME cylinder lubrication plant which lubricates the cylinders in the ME type engine.

The following displays can be <u>monitored</u>:

- 1.4.1 Flow (I/h)
- 1.4.2 Basic Feed Rate (g/kwh)
- 1.4.3 Actual Feed Rate (g/kWh)

The following displays can be operated at Chief level.

- 1.4.4 Total
- 1.4.5 Prelube
- 1.4.6 LCD
- 1.4.7 S% (Sulphur Content)
- 1.4.8 Feed Rate Factor
- 1.4.9 Min. Feed Rate (g/kWh)
- 1.4.10 Feed Rate Adjust Factor
- 1.4.11 Running In (g/kWh)

1.4.12 Lubricator Test Sequence



The latest Service Letter from MAN Diesel & Turbo should be consulted with regards to feedrate adjustments and settings.

1.4.1 Flow

The Flow display shows the ordered lube oil amount in litres/hour.



If one or more lubricators are malfunctioning (e.g. Feedback Failure) the actual amount applied will differ.

1.4.2 Basic Feed Rate

The Basic Feed Rate is a calculated rate for the complete lubricator system in g/kWh shown with two (2) decimals. The formula for calculating the Basic Feed Rate is = S% x (FEED RATE FACTOR).

1.4.3 Actual Feed Rate (each cylinder)

The bar graphs for each individual LCD shows the actual feed rate per cylinder. When running at low load the full bar is barred and the upper display on the bar graph shows "Low Load".

1.4.4 Total

The Total display shows the total ordered amount of lubricating oil used since last power up of the ECU involved. Pressing this display opens a toolbar with the option to reset the total amount of lubricating oil.

Both of the values Flow and Total are based on the ordered numbers of lubrication strokes and the displaced amount per stroke.

1.4.5 Prelube (for test purpose)

As stated above this button is mainly used for test purposes, since the prepare start will cause the system to automatically perform a prelube.

When the "Prelube" button is pressed a toolbar is shown on the screen.Pressing the button "ON" triggers a prelubrication on all cylinders and evaluates feedback from the lubricators.



Prelubrication can only be activated if hydraulic pressure is present. This demands that the engine (Sub-telegraph) is put in the state "Standby" or that the Hydraulic start-up pumps are set at manual operation and started.

1.4.6 LCD

The LCD display shows whether the LCD (Load Change Dependent) lubrication is on or off. When the LCD button is pressed, a toolbar will be displayed which will allow the operator to disable the LCD.

1.4.7 S %

Activating the display S % enables adjustment of the Sulphur content equal to the

sulphur content in the HFO used. The range is between 0.00 to 5.00 S % and is not adjustable outside this range.

1.4.8 Feed Rate Factor

Activating the display Feed Rate Factor enables adjustment of the feed rate for all cylinders. The display shows the feed rate with 2 decimals and is "g/kWh%S".

1.4.9 Min. Feed Rate

The display Min. Feed Rate enables adjustment of the minimum feed rate for all cylinders. The value is displayed in g/kWh and is normally set to 60% of the basic recommended feed rate.

1.4.10 Feed Rate Adjust Factor

Activating the display Feed Rate Adjust Factor enables adjustment of the feed rate for each cylinder separately.

1.4.11 Running in [g/kWh]

When a cylinder is being run-in, the feed rate can be entered by this display. Running-in of a single cylinder is described in Section 707-01 in the operation manual. The latest service letter from MAN Diesel & Turbo should be consulted as mentioned earlier.

1.4.12 Lubricator Test Sequence

Pressing the Lubricator Test Sequence starts a continuous activation of the lubricator at predefined injection rate (different from "Prelube" 1.4.5 where the injection of oil is done at the fastest possible speed.)

This feature is used after repairs, etc. on the lubricator(s), enabling the engineer to manually check the lubricator for leaks and injection.

If a single button (cylinder 1, 2, 3, etc.) is pressed, a toolbar is shown on the screen. The toolbar enables the engineer to start test of the lubrication on the particular cylinder concerned or on all lubricators.

In case of CCU failure (and the CCU can not be replaced immediately) please see instruction S903-0031 for how to obtain the back-up signal for lubrication.



The lubricator test can only be activated if hydraulic pressure is present. This requires that the engine (Telegraph) is put in state "Standby" or that the Hydraulic start-up pumps are set at manual operation and started.

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1. Maintenance

The maintenance screens give an overall view of the status of the ECS system seen on the following three screens. Plates 70332 – 70333 – 70334.

- 1.1 MPC description
- 1.2 System View I/O Test
- 1.3 Invalidated Inputs
- 1.4 Network Status
- 1.5 Function Test
- 1.6 Troubleshooting

The above-mentioned five maintenance screens can be accessed via the secondary navigator by pressing the "Maintenance" button in the main navigator. They are mainly used at engine commissioning, during fault finding on I/O cabling/ channels and external connections to sensors and during engine operation. The use of these screens is therefore relevant for engine crew as well.

1.1 MPC description

To understand the use of these screens, an explanation of the layout of the Multi Purpose Controller (MPC) is appropriate.

The MPC is a computer unit which has no user interface such as a display or a keyboard, but has a wide variety of inputs/outputs (I/O) for interfacing to sensors and actuators of the engine, e.g.: (see drawing next page).

- Inputs for e.g. tacho signals, standard (0)4-20mA transducers, ±10V signals, switches and 24V binary signals
- Outputs such as (0)4-20mA and ±10V signals, contacts and high-speed semiconductor switches.
- Duplicated Control Network for security
- Serial communication controller for either a Remote I/O Network or point-to point serial communication.
- Service channel to be connected to a laptop PC for service purposes.



The main processor of the Multi Purpose Controller is a Motorola 68332, which is a 32-bit processor and widely used in the automotive industry. It includes an on-chip timing coprocessor for synchronisation with the crankshaft rotation and speed measurement.

To ease the production of the Multi Purpose Controller, all programmable components are in-circuit programmable, which also allows field update of the controller by means of relatively simple tools. The MPC contains no harddisk or other sensitive mechanical components, and the software is stored in a non-volatile Flash-PROM memory, this allows for the application software to be sent to and programmed into the Multi Purpose Controller through the network, and thereby restore the functionality after the Multi Purpose Controller has been exchanged with a spare unit from stock.

The MPC is, as shown on the picture equipped with a battery. This battery is used for back-up power to the clock – watch of the MPC in the event that the 24 V power is turned-off. All clocks of all MPC's are synchronised via the network. Synchronisation is done regularly and always after power is on after a possible power off. Regarding battery in MPC: See S-instructions S906-0039 and S906-0040.

When a new MPC is mounted in the cabinet, the dongle in the cabinet is mounted in the dongle plug-in, after reconnection of all wires, and before connecting power. The dongle tells the "new" MPC in which cabinet it is mounted and, in that way, which software and parameters it should upload from the MOP harddisk (e.g. CCU1, ACU 3 or EICUA).

The MPC is also equipped with a light diode, capable of showing green, yellow or red light. This light tells the engineer what the status of the MPC is.

During normal running the diode is green. When the diode is yellow, the MPC is rebooting or is in Test or Configuration Mode. When the diode is red, the MPC is unavailable. If resetting does not solve the problem with the red diode then replacement of the MPC might be neccesary.



1.2 System View I/O Test (See Plate 70332)

The icons (plate 70332 1(4)) shown on the controllers, show the status of each single controller, e.g. whether it is in mode:

Active	1
Controlling	Cb
Test	T.
Configuration	C
Blocked	B
Not accessible	11

By pressing a single controller on this screen (in this case CCU1 is pressed and shown on Plate 70332 2(4)), the actual inputs/outputs on the selected controller are shown.

The screen shows Info, ID and Descriptions and process values of each single channel on the MPC.

It is possible to see each single channel in both Normal and Test Mode, but to set an output channel manually, Test Mode has to be chosen.

Changing to TEST Mode will STOP the MPC from controlling the system.

By pressing the channel number to the left of the individual channel, for instance screen 3(4) on Plate 70332, a single channel is shown (in this case, channel 30 on CCU1). The status and values of this channel are listed on this screen.

From this screen, input channels can be invalidated and validated again see page 4(4) on Plate 70332 (Chief Level).

Changing the status of a channel may cause the system to malfunction.

The reason for alarm on an input could for instance be a defective sensor or loose wiring from the sensor to the MPC.

If a channel is invalidated, the ECS will continue to operate in the best possible way, without the invalidated input sensor value.

1.3 Invalidated Inputs (See Plate 70333)

If an input channel is invalidated (as described in Section 1.2 above), it is listed on the screen "Invalidated Inputs". ID number, signal ID and a short description to easily overview and recognise the channel(s) involved are shown on this screen.

The "Invalidated Inputs" screen is an overview helping the engineer look through and control which channels are invalidated.

Input Channels Invalidated can be validated from this screen (Chief Level).



Changing the status of a channel may cause the system to malfunction.

1.4 Network Status (See Plate 70334)

This screen gives the engineer an overall view and exact status of the Control Network of the ECS

From this screen, it is possible to see the status of the Network using the icons named below: (Icons are visible at Plate 70334, bottom)

•	ОК	4
•	This MOP	\Box
•	No Reply Single Channel	1
•	No Communication	1
•	Not Accessible	$^{\prime\prime}$
•	On-line But No Information	11
•	Not Relevant	
•	Reference	B
•	Cross Connection	A

When all fields are shown with a green $\sqrt{}$ (check mark) everything is okay.

1.5 Function Test (See Plate 70348)

The Function Test tab consists of 3 items (submenus),

- 1.5.1 HCU for each cylinder
- 1.5.2 Tacho Equipment
- 1.5.3 HPS for each pump

The main purpose of these three screens, is to provide the engine personnel with a tool to test the function of the HCU, HPS and tacho equipment and their related components. Also the function test screens are used when replaced components are to be calibrated, e.g. in case of replacement of a fuel plunger sensor.

The function test screens are made as a step-by-step procedure, guiding the engine personnel through the tests. Each test begins with a few preparation steps in order to ensure the right conditions before commencing the actual test. The MOP must be in chief access level and if not otherwise stated, the engine must be stopped before commencing the test.



When rebooting an MPC in test mode, multiple alarms irrelevant to the test may occur.

1.5.1. HCU

The HCU tab is focusing on the FIVA valve. Depending on the configuration, the list contains three or two function tests. Only the FIVA valves with external amplifier have the option of an Amplifier Test. In the following all three function tests are explained.

NOTE

As the HCU function test list is longer than the height of the screen a scrollbar is placed to the right.

Preparation of HCU Test

To begin the function test press the button START and follow the steps on the screen.

NOTE

In order to verify that the fuel booster or exhaust valve are functioning as expected, an assistant must be stationed on the engine top at the unit in question during the test. For this test fuel pressure must be present.

Test of FIVA valve and calibration of Fuel Plunger

If the CCU MPC is not in test mode when the START button is pressed, the engineer is prompted to switch to test mode and reboot the MPC. Once the MPC has been rebooted, the function test will continue.



For testing of the fuel injection components, the FIVA will make one fuel injection.

The fuel injection is verified by the assistant on the engine top by feeling the shockwave on the respective fuel injection pipe, and feeling on the high pressure pipes.

For testing the exhaust valve components, the FIVA will activate the respective exhaust valve once. This is verified by the assistant, by listening for the "thump" sound of the exhaust valve opening and closing.

The test values are listed on blue background in the far right column when the function test is finished and will under normal circumstances be within the default reference range listed next to the test value column.

If for some reason the test value differs from the reference value, this will be shown in one of the following ways:

x.xV	Signal and value ok.
	Signal not present. (check if the MPC is connected to the network)
x.x mA	Signal value outside reference range. (Value electrically out of range or wire-break)
x.xV	Signal value outside reference range. (Signal ok, unit mechanically out of range)

703-17

If the test is successfully completed then the user has the option to use the SAVE button to upload the new calibration setpoints to the MPCs. Should the save operation fail then another attempt should be made after approximately 30 seconds.

Amplifier test (only applicable to Curtis Wright FIVA valves)

This amplifier test enables the engineer to test the FIVA amplifier. When the START button is pressed a set of adjustment buttons will appear on the toolbar.

The adjustment voltage range for channel 70 lies between -3.6V to +3.6V. If signal value field for ch. 70 turns red, this normally indicates that something is wrong with the MPC

The signal value field for ch. 33 has the same different types of error indications as shown above. If any of these are triggered then this most likely indicates that something is wrong with either the amplifier or the connections to the amplifier.



When testing the amplifier with voltages in the high end of the adjustment voltage range, deployment of the fuel booster may occur, resulting in fuel injection

Cyclic Test of Exhaust Valve and/or fuel injections

When START button is pressed, a set of buttons will appear on the toolbar, which enables the engineer to start a repeated cyclic test of the exhaust valve, in other words, the exhaust valve will continue opening and closing until the STOP button is pressed. Also for the fuel booster a single injection test is possible (both during the cyclic test and independent of this).

Activation of "single injection" will lead to one full MCR fuel Injection in the cylinder. Several activation will lead to filling of the combustion with fuel oil.

Reboot of CCU

Reboot the CCU MPC to test mode in order to continue with tests or reboot to set the CCU MPC to normal operating mode (finished with function tests).

1.5.2. Tacho

The Tacho Test allows for the verification of the angles of the Tacho Pick-Ups and angle encoder fine adjustment of certain parameters.

Pre-Start Test

Press Start and follow the instructions on the screen. Make sure that an assistant is standing by to activate the Turning Gear, and verify the crankshaft position.

During the test the following is displayed on the screen:

A: xx B: xx (blue background): If the crank has been turned to the prescribed angle when the background is blue, then the value is correct. Continue to next step.

A: xx B: xx (yellow background):

If the crank has been turned to the prescribed angle and the background is still yellow, then the test has failed. Continuation of the test is not possible. By pressing the details button, specific information regarding the failure is displayed. Check and adjust the Tacho arrangement.

The x in the test can be either T or F

Setting of Fine Adjustment Parameters

As indicated on the screen a certain minimum engine speed is required in order for the ME system to measure a correct 'delta Tacho-B' value.

The 'Trigg Offset AH' value that is to be entered must be taken from the PMI equipment (see PMI manual). The 'Trigg Offset AH' value is not measured by the ME system, that is why a PMI-0 diagram is required as part of the setting of the final Tacho parameters.

1.5.3. HPS

The HPS function Test allows for the test and calibration of the hydraulic pumps. Up to 5 pumps can be present depending on system configuration, each tab corresponds to a pump.

Preparation

To start the test press " Start " and make sure that a start-up pump is in local control on the starter cabinet, and running so that the necessary hydraulic pressure can be maintained.

Test

Press " Start " and follow the instructions on the screen. Make sure an assistant

is standing by at the pump to check the swash plate angle.

During the test the following is shown on the screen:

Icons with background colours can be seen in chapter 1.5.1

x.x mA (blue background): value ok - go to next step.

x.x mA (red background): value is outside the measurement interval (4-20mA) continuation of the test not possible - check the sensor and cables.

x.x mA (yellow background): value differentiates from the reference value. Continuation of the test not possible. Check the sensor.

If all of the steps are satisfactory calibration of the specific pump is carried out by pressing " Save ". The test is concluded by rebooting the MPC back to Normal Mode.

1.6 Troubleshooting (See Plate 70349)

This screen is used for performing troubleshooting on the Hydraulic Cylinder Unit and Hydraulic Power System. The HCU Events and HPS Events are used to show the actual movements of FIVA valve, plunger positions, exhaust valve movements and swash plate positions in graphs.

1.6.1 HCU (See plate 70349 page 1-5)

On this screen FIVA activation can be performed to execute fuel plunger and exhaust valve movement to check whether the system is working correctly.

Activation of the FIVA is performed by changing MPC Mode into Test Mode and activating the buttons displayed in the toolbar.

The cyclic test is only a cyclic activation of the exhaust valve.

Activation must only be performed with stopped engine. Each activation of the fuel plunger results in a fuel injection into the cylinder.

1.6.2 HPS (See plate 70349 page 6)

On this screen the swash plate position for each pump can be regulated to check whether the system is working correctly.

Activation of the swash plate position is performed by changing MPC Mode into Test Mode and activating the buttons displayed in the toolbar.

The swash plate position can be seen on input ch 34 and compared with the desired setpoint.

When finish testing put MPC back to normal mode.

1.6.3 HCU and HPS Events (See plate 70349 page 7-8) (Only available on MOP B)

These screens are an aid for the engineer and are used to monitor the actual movements of the HCU and HPS related signal. E.g. used to identify trouble in case of a malfunction of the electrical and mechanical components.

The HCU and HPS Events include a lot of very useful information for e.g. troubleshooting.

It can however in certain cases be difficult to make quantitative conclusions based on HCU and/or HPS Events logs taken during a situation where problems are present (e.g. deviating cylinder pressures, hunting hydraulic pressure, etc.).

In those cases it is very helpful to have HCU and HPS Events logs from periods where there were no problems or irregularities. By comparing these logs with logs from situations where problems are present it is often possible to make qualitative conclusions regarding the current problems.

Therefore it is recommended to take manual HCU and HPS Events logs from time to time when no problems or malfunctions are present.

A suggested procedure is to make a note regarding the current speed, index and internal estimated power together with the names of the HCU and HPS Event logs and then save these on either a USB stick or some other computer (so the logs are still available even if MOP-B is later replaced).

NOTE

Always ensure that any USB memory stick inserted into the MOP is scanned and cleaned of any malware.

A list of available dumps can be found in the upper left part of the list - newest on top. To display the contents mark an element in the list and press "Show Sequence".

Both manual dumps (*Log Manually*) and automatic dumps can be performed for special failures/alarms .

The event which caused the dump is described in the text above the graph area. The time of alarm is shown as a vertical dashed line. The display of measured values can be turned on and off by pressing the buttons on the left side of the screen.

By clicking and holding *(the cursor turns into a hand)* in the area left of the Y- axis or in the area below the X - axis, the graph can be moved vertically or horizontally.

Zooming can be carried out by drawing a square in the graph area while "default view" can be recalled by pressing " Zoom to fit "

Storing both PMI diagrams and HCU Events logs from days with no problems, will greatly improve the options available for later troubleshooting. Therefore it is a good idea to take the HCU Events logs together with Performance Measurements and then save it all together.

1.6.4 CoCoS EDS

As described on Plate 70319 MOP B is connected to the CoCoS EDS PC (which also runs the PMI software).

CoCoS EDS is not a part of the ECS, however it is an essential tool with regards to troubleshooting and diagnostics.

Therefore it is important that CoCoS EDS is running correctly and that the connection is functioning. All the time.

The CoCoS EDS installation includes guidance on how to evaluate and troubleshoot the connection.

1.6.5 Data logging

In the case that assistance from external parties is needed, it is essential for trouble shooting that following data is delivered to external parties:

- A clear description of the case
- ECS Alarm/Event Log
- ECS parameter file (Spaf)
- ECS HCU data logger files
- ECS HPS data logger files
- EDS data logger files

Al this information can be gathered automatically with a program called "DatGat.exe" that is found on the CoCoS-EDS CD. A description on how to use the "DatGat.exe" program can also be found on the CoCoS-EDS CD. The program can also be downloaded from the following adress : **Https//dieselport.mandiesel.com**



The above mentioned data and logfiles will contribute to speed up the troubleshooting process, and are for that reason very important for external parties

1. System

The screens are:

1.1 Set Time

1.2 Version (software and IMO Check Sum)

1.1 Set Time (See Plate 70335)

At the Set Time screen, the operator is able to set the time/date for UTC (Chief Level required) or to set the time offset for Local Time in intervals down to 5 minutes.

Pressing on either button "UTC Date/Time" or button "Local Date/Time" will display toolbars (shown on Plate 70335). From these toolbars, Date and Time can be set.

Pressing the buttons "UTC Time displayed" or "Local Time Displayed" enables the operator to choose between the time to be displayed at the MOP panel (upper right corner) and in the lists (alarm list, event log etc.)

Alarms and logs are recorded with both Local Time/Date and UTC Time/Date regardless of which time/date is selected for displayed .



Always ensure a correct setting of UTC. The ECS has no connections to the ship's master clock

- 1.2 Version (See Plate 70336)
- 1.2.1 Background

This screen displays the version type of the ECS controlling the ME engine. It displays, in table format, all the controllers that comprise the system, including specific information relating to each controller.

1.2.2 Screen Items

In the upper system information line, general information of the ECS system for this particular engine is shown. The fields are: (See Plate 70336)

Product Name & Version	The name and version of the ECS software
Engine Group No. IMO No	The Engine number of the engine builder Engine IMO number (former Lloyds number)
Engine Builder	Name of engine builder
Eng. No.	Engine Serial number

1.2.3 Controller information

In the Controller information pane, data for each Controller in the system is dislayed. The pane contains the following:

1.2.4 Controller unit

ID	Name of MPC (controller)
Addr.	Network Address of MPC
Туре	Application group the MPC belongs to (ACU, CCU, ECU, EICU or SCU)

1.2.5 Parameters Check Sums

The Parameter Check Sums are indications of the current parameter values in the ME system. They are used as a method for determining if parameters have been changed. Especially the IMO Design parameters must not be changed compared to shop trial values, since they control emission and performance relevant parameters.

No changes made on the MOP will change the IMO Design Parameters Check Sums.



It is not possible to recreate the parameters of the ME system from the Check Sums, therefore sending a screen dump of this screen is not sufficient for external parties who inquire about specific parameter values.

1.2.6 Using the Screen

When the screen is first displayed, no information appears on the table. Press the "Refresh" button to retrieve the system information and parameter checksums of all controllers connected to the ECS. (See plate 70336.)

If at least one controller supplies information on the system that does not agree with the other controllers, a warning message is displayed in yellow in the specific controller unit and at the toolbar.

Pressing the Export button generates a hardcopy of the information displayed in the table that can be saved to a hard drive or USB memory stick. This exported file is compressed in Zip format and must be unpacked to be readable. The file format is:

SWVersNParamChecksums on <Date & Time> for <MOP> <SW-version> on IMO <IMO number> Engine no <Engine number>.zip



Always ensure that any USB memory stick inserted into the MOP is scanned and cleaned of any malware.

1.3 Power Off

The Power Off button acts the same way as the "Shut Down" button in Windows Operating Systems on PCs.

Disclaimer regarding the ECS Screenshots

The following section of this manual includes a series of plates showing images of the MOP screens.

These plates are used for reference in the other parts of manual and are a strong visual aid in understanding and getting familiar with the ECS.

It is important to realize that the purpose of these screenshots is to illustrate the ECS user interface in a qualitative way – not to give quantitative information regarding the process control and feedback loops. The values displayed will not always be consistent with those experienced on a real plant.

These discrepancies include (but are not limited to) the number of active alarms, process values and set points.



Always consult the specific plant in order to get the precise layout of the MOP screens.

No HPS _blower feedback from ACU3	Alarm	ECUB_011424	12:59:48	(b) (2) 48 0
Alarms Alarm List		2010-02-05 13:0)2:25	Alarms I
Ack Description	Status	QI	Time	Alarm
 GROUP: Too many HP Pump Failures 	Aarm	GROUP-TMPF-EICU	13:01:55	LIST
 GROUP: Changing pressure controling pump 	Aarm	GROUP-CPCPD-ECU	13:01:55	Event
() Suprv. Ch31,1201-2,Hydraulic Pressu	Normal	ACU2_1201-204	13:01:54	Log
() Suprv. Ch31,1201-1,Hydraulic Pressu	Normal	ACU1_1201-104	13:01:53	
 GROUP: Hydraulic HP Pump Failed on ACU3 	Aarm	GROUP-HHP3-EICU	12:59:55	Manual Cut-Out
 GROUP: ACU3 not in Normal mode 	Aarm	GROUP-AR-ACU3	12:59:52	List
GROUP: ACU3 not available	Aarm	GROUP-NA-ACU3	12:59:52	Channel
() MPC ACU3 unavailable	Alarm	EICUA_SNA-ACU3	12:59:51	LIST
() MPC ACU3 unavailable	Aarm	EICUB_SNA-ACU3	12:59:51	Engine
COUP: Net A not connected to ACU3	Aarm	GROUP-N0-ACU3	12:59:52	D
() Net A not connected to ACU3	Aarm	EICUA_SN0-ACU3	12:59:51	
() Net A not connected to ACU3	Alarm	EICUB_SN0-ACU3	12:59:51	Auxiliaries
GROUP: Net B not connected to ACU3	Aarm	GROUP-N1-ACU3	12:59:52	
				Maintenance
				Admin
				Power Off ①
VAck. VAII Cut + Line/of ₩ 2 13 ₩			lufo	Access

	No HPS _blower	feedback from ACU3	Alarm	ECUB_011424	12:59:48	18 (12) 48 0
Alarm	ıs ▶ Alarm List			2010-02-05 13 :	02:59	Alarms >
Ack		Description	Status	Q	Time	Alarm
	Suprv. Ch31,	1201-2,Hydraulic Pressu	Normal	ACU2_1201-204	13:01:54	LIST
	Suprv. Ch31,	1201-1,Hydraulic Pressu	Normal	ACU1_1201-104	13:01:53	Event
	GROUP: Hyd	raulic HP Pump Failed on ACU3	Alarm	GROUP-HHP3-EICU	12:59:55	Log
<u>ا</u>		12 not in Mormal mode			12-50-53	Manual
GRG	OUP: Hydraulic H	P Pump Failed on ACU3 - GROUP-HHP3-EICU			>	Cut-Out List
_	Description:	Hydraulic high pressure pump does not work correctly			<	Channel List
Ŭ	Cause:	 Hydraufic pump failure, or MPC not running in normal mode, or Network failure 				Engine
	Effect:	Swash plate moves to fail safe position (maximum flow in al	head direct	ion)		Auviliariae
		Running ahead: No effect on engine performance.				
		Hydraulic pressure may increase. Running astern:	a subsection of the		•	Maintenance
	Action:	Check: - Other alarms to locate the root cause for the pump alarms	and and			Admin
		- I hat the MPC is in normal running mode				
						Power Off ①
	Ack.	Cut + Line/of 5 13			Info	Access

		_	_	v -		-	_	_	-		R										1			
10 12 48	Alarms 🕨	Alarm		Event	Log		Manual Cut-Out	List	Channel	List		Engine		Auxiliaries			maintenance		Admin				Power Off	Access
59:48		20 Ack									×	×	×	×	×	×	×	×	×	×	×	×		Info
12:5	3:04:45	MCo AC																						144
424	02-05 1	Status	<u>Event</u>	Event	Event	Event	Event	Event	Event	Event	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal		•
Alarm ECUB_011	2010-(-		08 209 started. Not si	£	ls <*>	g for threads <*>	vised <*>					tency					tency						•
		Description	nabled	2.168.0.103 1000 2	ed. Not supervised <	d. Waiting for thread)3 - 2 started. Waitin	c started. Not supen	ardware established	j disabled	cation failure	mmunication fail	Y-AT_SEA Inconsist	i Selected	stop Cmd Bridge'	Speed Set Bridge'	Slaw Dawn Cmd'	3Y-AT_SEA Inconsist	Selected	Stop Cmd Bridge'	Speed Set Bridge'	Slaw Dawn Cmd'		•
			Watchdog e	pmi_bridge 19	MainApp start	esydjob starte	bes_server 20	MOPLock -h -	Contact with h	HW Watchdog	RCS communi	RCS serial cor	FWE-STANDB	No Ctrl Station	Lock in Last 'S	Lock in Last 'S	Lock in Last 'S	FWE-STANDB	No Ctrl Station	Lock in Last 'S	Lock in Last 'S	Lock in Last 'S		Export
ACU3		Time	<u>238,53,52</u>	2:38:53,52	2:38:53,52	2:38:46,55	2:38:41,04	2:38:41,04	2:38:40,54	2:38:36,16	8:38:47,17	8:38:45,54	8:38:40,91	8:38:40,90	8:38:40,89	8:38:40,89	8:38:40,79	8:38:40,68	3:38:40,67	8:38:40,66	8:38:40,66	3:38:40,66		
dback from		Date	<u>010-02-05 12</u>	010-02-05 1	010-02-05 1:	010-02-05 1	010-02-05 1	010-02-05 1	010-02-05 1	010-02-05 1	010-02-04 1	010-02-04 1	010-02-04 1	010-02-04 1	010-02-04 1	010-02-04 1	010-02-04 1	010-02-04 1	010-02-04 1	010-02-04 1	010-02-04 1	010-02-04 1		Date/Tim
olower fee	it Log		206 2	0G 2	0G 2	G 2	0G 2	0G 2	DG 2	0G 2	2	2	2	2	2	2	2	2	2	2	2	2		Time Spar Filter
1 SQH ON 🕕	Alarms < Even	ID: Unit_Tag	MOPB WATCHL	MOPB_WATCHDC	MOPB_WATCHDC	MOPB_WATCHDC	MOPB_WATCHDC	MOPB_WATCHDC	MOPB_WATCHDC	MOPB_WATCHDC	EICUB_RCSVarAA	EICUB_SMBsTOAI	EICUB_0931	EICUB_0660	EICUB_0158	EICUB_0156	EICUB_0155	EICUA_0931	EICUA_0660	EICUA_0158	EICUA_0156	EICUA_0155		Unit/Tag Filter

Edition 0004

	Description Status MCo Iash Normal Normal Iash Normal Normal I rate Normal Normal
Description	Flash d rate d rate
orrupt rometer Flash	d rate d rate
ararmeter Flash dard baud rate	d rate
dard baud rate	
	ar
dard be dard be	ġ
stan	sh. Cle
83 Invalia 83 Non st 83 Non st	Fetcl
12:49:53,	
0-02-03	Tag
2010	ndex
d d Filter	
Init_Ta IDKEY SIPF badBauc badBauc	

When referring to this page, please quote Plate 70321 Edition 0004

No HPS _blower fi	eedback fror	m ACU3	Alarm E	CUB_011424	12:59:48	18 (12) 48 0
Event Log				2010-02-05 13:0)6:48	Alarms >
nit_Tag	Date	Time	Description	Status MC	to ACo Ack	Alarm
DKEY	2010-02-03	12:49:53,84	ID Key corrupt	Normal	×	LIST
SIPF	2010-02-03	12:49:53,83	Invalid Parameter Flash	Normal	×	Event
badBaud	2010-02-03	12:49:53,83	Non standard baud rate	Normal	×	Log
bedBaud	2010-02-03	12:49:53,83	Non standard baud rate	Normal	×	
Time Span Filter				yyyy-mm-dd / hh:	× ×	Manual Cut-Out
From Date 2010-01-31	From Time 00:00:00	To Date 2100-01-	-31 To Time Clear	Apply		List Channel List
7	e 1	4	6 7 8 9	•	BS	Engine
Ø	ш _	٣	0 - -	-	1	Auxiliaries
×	s	-	L C	•••	×	Maintenance
/ Z	×	C	<pre> N M </pre>	Spa	Ce	Admin
WATCHDOG WATCHDOG	2010-02-05 2010-02-05	12:38:41,04 12:38:41,04	bes_server 203 - 2 started. Waiting for threads MOPLock -h -c started. Not supervised <*>	Event Event		
						Power Off ()
ttrag Time Sp itter	an Go t	eme	Export		Info	Access

48 0	•			ſ		Ĩ	- =	-	Ì.	ries	nance			off ()	•==
3	Alarms	Alarm	LISI	Event	Log		Manua Cut-Ou	Channe	Engine	Auxilia	Mainte	Admin		Power	Acces
9:48		D Ack	×	×	×	×	×	$ \times \times $	××	××××	×				Info
12:5	07:56	Do AC					-mm:		- BS	1		ce			
	5 13:(us Mo	la l	lar	lai	lar	hh / bb	1	+	1		Spa	2 E		
11424)-02-0	Stat	Norn	Norn	Norr	Norm		Go to	1			\square	Evel Evel		•
3UB_0	2010						YVY.		0		_		£		
Ŭ										0		•	threads		
Ala		ion							6	-	×	Σ	iting for ervised		
		script							œ		7		ted. Wai Not sup		•
		ă		er Flash	aud rate	aud rate			2		I	Z	- 2 star started.		
			corrupt	arametr	ndard b	ndard b				~		8	ver 203 ck -h -c		
			ID Key o	Invalid F	Non sta	Non sta			9	F		>	bes_ser MOPLo		Export.
13		ше	53,84	53,83	53,83	53,83		ar	2		۳.		41,04 41,04		
om AC		F	12:49	12:49	12:49	12:49		Cle	4	<u> </u>	٥	0	12:38		time
ack fro		ate	0-02-03	0-02-03	0-02-03	0-02-03		00:00		ш		×	-02-05 -02-05		Go Date/
r feedb	5	-	201(201	201(201(- a	iii iii		3	s	z	2010		Span er
blowe	nt Lo						tte/Tim	01-31	8		۲		88		Filt
S HPS	► Eve	it_Tag	KEY	Ъ	adBaud	adBaud	o to Da	ate 2010-(-	0	*		VATCHD		Tag
ž O	Alarms	D: Uni	ACU3_ID	kcu3_SI	scus_b	cue_b	S	8 8 8	ā ā	5 5 5	NOP		AOPB_V		Unit

Page 4 (4)
() No HPS _blower	feedback fro	m ACU3		Alarm ECUB_0	11424	12:	59:48	(B) (2) 48 0
Alarms > Manual Ci	ut-Out List			201(0-02-05	3:08:2	8	Alarms >
Q	Date	Time	Description		Status	Limit	Current	Alarm
EICUB_130151	2010-02-05	12:55:13	Cyl 12. No Cylinder lubrication		Normel	÷		LISI
EICUB_130150	2010-02-05	12:55:13	Cyl 11. No Cylinder lubrication		Normal			Event
EICUB_130149	2010-02-05	12:55:13	Cyl 10. No Cylinder lubrication		Normal	÷	÷	Log
EICUB_130148	2010-02-05	12:55:13	Cyl 9. No Cylinder lubrication		Normal			Manual
EICUB_130147	2010-02-05	12:55:13	Cyl 8. No Cylinder lubrication		Normal	÷	÷	Cut-Out
EICUB_130145	2010-02-05	12:55:13	Cyl 6. No Cylinder lubrication		Normal			Change
EICUB_130144	2010-02-05	12:55:13	Cyl 5. No Cylinder lubrication		Normel	÷	÷	Crannel List
EICUB_130142	2010-02-05	12:55:11	Cyl 3. No Cylinder lubrication		Normal			
EICUB_130143	2010-02-05	12:55:06	Cyl 4. No Cylinder lubrication		Normel	÷	÷	Engine
EICUB_130146	2010-02-05	12:55:06	Cyl 7. No Cylinder lubrication		Normal			
EICUB_SEICU	2010-02-04	18:28:02	Global Params. inconsist		Alarm	÷	÷	Auxiliaries
EICUA_SEICU	2010-02-04	18:26:53	Global Params. inconsist		Alarm			
EICUA_130151	2010-02-04	18:25:24	Cyl 12. No Cylinder lubrication		Normel	÷	÷	Maintenance
EICUA_130150	2010-02-04	18:25:24	Cyl 11. No Cylinder lubrication		Normal			
EICUA_130149	2010-02-04	18:25:24	Cyl 10. No Cylinder lubrication		Normal	÷	÷	Admin
EICUA_130148	2010-02-04	18:25:24	Cyl 9. No Cylinder lubrication		Normal			
EICUA_130147	2010-02-04	18:25:24	Cyl 8. No Cylinder lubrication		Normal	÷	÷	
EICUA_130146	2010-02-04	18:25:24	Cyl 7. No Cylinder lubrication		Normal			
FICUA 130145	2010-02-04	18-25-24	Cvl 6 No Cylinder lubrication		Normal			
								Power Off ①
Reactivate		Line	^{i/of} - 48 ▼ ▼	•		144	Info	Access

Edition 0004

12 48 0	us ▶	E					ual Dut	5	Inel			ne		liaries			itenance		in					er off ①	• ==
ē	Alar	Alar		Š	ŝ		Man	List	Chai	List		Engi		Auxi			main		Adm					Pow	Acce
2:59:48	4	VCo Ack	×	×	×	×	×	×	×	×	×	×	×	×	×	×		×	×	×	×	×	×		linfo
<u> </u>	13:08:	MCo A																							
11424	0-02-05	Status	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal		••
ECUB_0	201(
Alarm		_										dis	eng	ve	e,		ssu	do s	aur	uwo	9	SS			
		scription	A L	JB				_	down level)			rning gear	rning gear	in start val	in start val	ort air dist l	draulic Pre-	stem bypas	be oil press	leak shutd	arting air pr	ntrol air pre			
		ă	s from ECI	s from ECL	ailed	ailed	Ð	Ctrl Failed	age (shut	ress. high	ress. low	109-A,Tu	110-A,Tu	1111-A,Ma	112-A,Ma	116-A,Ste	201-1,Hy	202-A,Sys	204-1,Lut	236,Hyd.	501-A,Sta	503-A,Co			
			No Commands	No Commands	Blower 1 Ctrl F	Blower 4 Ctrl F	Pump ctrl failu	Startup Pump	Hydraulic leak	Double pipe p	Double pipe p	Supry. Ch23,1	Suprv. Ch22,1	Suprv. Ch21,1	Suprv. Ch24,1	Supry. Ch25,1	Supry. Ch31,1	Suprv. Ch80,1	Suprv. Ch32,1	Suprv. Ch27,1	Suprv. Ch37,8	Suprv. Ch36,8	ID Key corrupt		/of - 1264
n ACU3		Time	12:51:39	12:56:16	16:28:25	16:28:25	12:50:03	14:23:14	10:18:37	12:50:04	12:50:04	12:49:58	12:49:58	12:49:58	14:10:12	12:49:58	13:02:15	12:50:00	12:49:59	12:49:58	16:58:21	14:41:18	12:49:56		Line
feedback fror	ist	Date	2010-02-03	2010-02-05	2010-02-03	2010-02-03	2010-02-03	2010-02-03	2010-02-05	2010-02-03	2010-02-03	2010-02-03	2010-02-03	2010-02-03	2010-02-03	2010-02-03	2010-02-05	2010-02-03	2010-02-03	2010-02-03	2010-02-04	2010-02-04	2010-02-03		tivate
blower	annel Li																								Read
SOLI NO HPS	Alarms IN Ch8	9	ACU1_010110	ACU1_010111	ACU1_0210	ACU1_0510	ACU1_070119	ACU1_070210	ACU1_0708	ACU1_0724	ACU1_0725	ACU1_1109-A04	ACU1_1110-A04	ACU1_1111-A04	ACU1_1112-A04	ACU1_1116-A04	ACU1_1201-104	ACU1_1202-A03	ACU1_1204-104	ACU1_123604	ACU1_8501-A04	ACU1_8503-A04	ACU1 IDKEY		cut-out

MOP Channel List

Edition 0004

								0 4 27 0
Engir	_{ne} ▶ Operati	n				2011-06-29 11:53	3:19	Alarms
	Main State		Command [R	[M]	Speed [RPM]	Fuel Index [%	[
	Standby		Bridge	-11.5	Speed Modifier	Index limiter		Engine 🕨
			ECR	184.0		Chief		Operation
	Increased	limitation	LOP	125.8	Set Point Actual	Limiter Actu	al	
	Running Mod	0	Governor Mo	de	184.0 183.7	110	66	Status
	Econ	omy	RPM (Control	///			
	Start Air	Inlet Oil	Hyd. Oil	Scav. Air	200 - 200			Process
	32.3 Bar	2.8 Bar	206 Bar	2.90 Bar	150 -	100 -		Information
	30 -	1		4	100	I I I I 000		Process Adiustment
	20	I I CO	225	I CO		1		
	1	2		2	2	1 90		Chief Limiters
	10	1 1 5-	175 -	1	• • • • •	1		
	0	- 0	- 150 -	- 0	- 20	40 -		Auxiliaries
	HPS	Lubricator	Auxiliary Blo	wers	-100 -	1		Maintenance
	Auto	Running	Auto	Stopped	-150 -	20 -		
	PTO	WHR			1 1 1	I c		Admin
	Allowed	ġ			Z = 002-			
Engi	ne Start							Power Off ①
	Start Status Run	ning			Prepare Start	Turn Auto	Air Rim	Access

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Plate 70324

									0 0 48 0
Engi	ne ▶ Operati	uo					2010-02-12 1	0:14:23	Alarms
	Main State		Command	[RPM]		Speed [RPM]	Fuel Inde	[%] X8	
	Standby		Bridge	_	101.1	Speed Modifier	Index limit	er	Engine >
			ECR		183.8		5	iief	Operation
			LOP	_	0.0	Set Point Actual	Limiter	Actual	
	Running Mod		Governor	Mode		^{183.8} 183.5	110	102	Status
	Econ	omy	Torq	ue Co	ntrol			,	
	Start Air	Inlet Oil	Hyd. Oil	Sc	av. Air	200 -			Process
	27.5 Bar	3.0 Bar	207 Bai	2 2	.69 Bar	150 -	100 -		Information
	30 -	4	250 -		4	100	I I 08		Process Adjustment
		- 00	225		а 1 1		}		
		2 -	200 -		2 -	00	- 09		Chief Limiters
	10 -	1	175 -		1		1		
	0	- - 0	150 -		- 0	-50 -	40 -		Auxiliaries
	SdH	Lubricator	Auxiliary 6	Blowers	-0	-100	1	1	Maintenance
	Auto	Running	Auto	55 T	opped	-150 -	20 -		
	PTO					-200	0		Admin
	5						l	l	
	apow Buin								Power Off
	Economy	Emis	sion	TO O	ut Out	Custom		×	Access Chief

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MAN B&W

						0 0 48 0
					2010-02-12 10:12:54	Alarms
		Command	[RPM]	Speed [RPM]	Fuel Index [%]	
		Bridge	101.1	Speed Modifier	Index limiter	Engine >
		ECR	183.8		Chief	Operation
		LOP	0.0	Set Point Actual	Limiter Actual	
2		Governor N RPM	Aode Control	183.9 184.1	110 104	Status
	ľ		,	200 - 20	I	
a o	Oil	Hyd. Oil 206 Bar	Scav. Air	150 -	100 -	Process Information
		360				
t c			i t c	100	- 80 -	Adjustment
o		- 077	1	50 - 3	1	
0		- 200 -	1		09	Chief Limiters
÷	1	175 -	1	5		Auviliarias
0		150 -	1 1 0	-20	40 -	
br	icator	Auxiliary BI	lowers	-100 - 2	•	Maintenance
اچ ا	ning	Auto	Stopped	-150 -	20	
				-200 - 200	- 0	Admin
						Power Off ①
	Torque	Control	Index Control		×	Access Chief
I.						

						0 0 48 0
Engine IN Opera	tion			2	010-02-05 13:09:40	Alarms
Main State		Command [F	[M]	Speed [RPM]	Fuel Index [%]	
Standby		Bridge	6 .66	Speed Modifier	Index limiter	Engine >
		ECR	0.0	Stabilising	Start	Operation
		LOP	0.0	Set Point Actual	Limiter Actual	
Running Mo	de	Governor Mo	ode	73.6 55.7	10 1 0	Status
Ш	nomy	RPM (Control	11		
Start Air	Inlet Oil	Hyd. Oil	Scav. Air	200 = 7	1	Process
35.3 Bar	2.6 Bar	183 Bar	0.01 Bar	150 -		Information
- 30 -	4 -	250	4	100	I I 08	Process
I I 00	1 1 10	225	1 1 1 1	Ţ	2	
	- 3 - 3		1 - 2		09	Chief Limiters
10 -	1	176 -	1	0		
0	1 1 0	150 -	- 0	-50 -		Auxiliaries
HPS	Lubricator	Auxiliary Blo	wers	-100 - 2	1	Maintenance
Auto	Running	Auto	Running	-150 -	20	
PTO Off				-200 - 200	- 0	Admin
Engine Start						Power Off ①
Start Status Ru	nning			Prepare Start Stow Tur	n Auto Air Run	Access

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0 0 48 0	Alarms		Engine I	Operation		Status		Process	Information	Process	Adjustment	Chief Limiters		Auxiliaries		Maintenance		Admin		Power Off ①	Access
	:29:20	Idex [%]	imiter	hief	Actual	101		Ţ													Air Run
	0-02-20 15	1 Fuel Ir	Index L	Ö	Limiter	109		• •	- 100 -	1	- 80 -			- 40 -		- 20-		0			Auto
	201(Pitch [%				2 100		100 -	- 08	- 09	40 -	20 -	0	-20 -	-40 -	- 09-	-80 -	-100 -			Slow Turn
		d [RPM]			nt Actual	0 184.		0 - <u>164</u>		- 0	- 0	1 1 1	10		- 0		1 1	1 5			are
		Spee			Set Poi	184		20	18	16	14	12	10	80	9	4	~	4			Prep Sta
		PM]	184	184	0.0	de	ontrol	Scav. Air	0.00 Bar	4	1 1 10	1	1	0	,	vers	Stopped				
		Command [R	Bridge	ECR	LOP	Governor Mo	RPM C	Hyd. Oil	177 Bar		225		476	150 -		Auxiliary Blov	Auto				
	Ę						h	Inlet Oil	3.0 Bar	4 +	1 1 10	1	1	, i		Lubricator	Stopped				ing
	Operation	Main State	Standby			Running Mode	Econ	Start Air	27.2 Bar	08	1	20	10	I I I I 0		IPS	Auto	PTO	5	e Start	Start Status Runn
	Engine					2														Engin	

Plate 70324

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MOP Status



MOP Status

MAN B&W

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MAN B&W

							0 0 48 0
Engine •	Process Inform	ation			2010-02-12	10:08:59	Alarms
Running	g Mode Sp	eed Control					
							Engine 🕨
							Operation
	Running	Mode	Spe	ed Set Point [RPM]	Speed Actual [RPM]		
		conomy		183.8	184.6		Status
	Estimate	ed Engine Load	Fue	I Index Set Point			
		100 %		103 %			Process
	Maximu	m Pressure	Hyd	1. Oil Set Point	Hyd. Oil Actual		
		140 Bar		207 Bar	207 Bar		Process
	Compre	ssion Pressure	Psc	av Set Point	Pscav Actual		Majusument
		130 Bar		2.93 Bar	2.69 Bar		Chief
	Pcomp/J	Pscav					Limiters
		35.5					Auxiliaries
	Exh. Val	ve Open Timing					
	F	0.9 °ATDC					Maintenance
							Admin
Running	Mode						Power Off ①
	conomy	Emission	TC Cut Out	Custom		×	Access Chief
J							and the second s

						0 4 27 0
Engine Process Info	ormation			2011-06	-29 11:54:37	Alarms
Running Mode	Speed Control					
						Engine >
Command [RPI	M] Fine Adj.	Speed Set [RPM]	Index Limit [%]	Fuel Index [%]	Speed [RPM]	Operation
ECR	184.0	184.0	110	66	183.2	
						Status
	Speed Modifier	0	overnor / Index Limite	Encine		
	Stabilising)+	Start			Process
	Stop		Chief			Information
	Minimum Speed		Scav. air pressure			Process
	Maximum Speed		Torque			Adjustment
	Fixed Speed Set		Hyd. Power Supply			Chief
	Shut Down		TC Cut Out			Limiters
	Slow Down					
	PTO					Auxiliaries
	Speed Ramp					Î
	Load Program					Maintenance
	Barred Speed rang	ge				
	RPM Fine Adjust					Admin
	Run Up/Down Prog					
	Chief Max Speed					Power Off ①
	TC Cut Out	Active N	fodifier 🕨 Active I	imiter D Near	est Limiter	Access
	WHR					

0 (4) 27 0	Alarms		12 Engine >	Operation		-0.7 Status		0 Process	Information	Process Adiustment	-0.5		Chief	Chief Limiters	Chief Limiters Auxiliaries	Chief Limiters Auxiliaries	Chief Limiters Auxiliaries -0.1 Maintenance	Chief Limiters Auxiliaries -0.1 Maintenance	0.0 Chief Limiters Auxiliaries Maintenance 0.0 Admin	0.0 Chief Limiters Auxiliaries 0.1 Maintenance	0.0 Chief Limiters Auxiliaries 0.1 Maintenance 0.0 Admin
	1:55:44		11			-0.7		0			-0.5			0.0	0.0	0.0	-0.1	-0.1	-0.1 0.0	0.0	0.0
	6-29 1		10			-0.7		0			-0.5			0.0	0:0	0:0	-0.1	-0.1	-0.1	0.0	0.0
	2011-0		6			-0.7		0			-0.5			0.0	0.0	0.0	-0.1	-0.1	-0.1	-0.1	-0.1
			8			-0.7		0			-0.5			0.0	0.0	0.0	-0.1	-0.1	-0.0 0.0	0.0	0.0
			2			-0.7		0			-0.5			0.0	0.0	0:0	0.0	-0.1	0.0 -0.1	0.0 -0.1	0.0
			9			-0.7		0			-0.6			0.0	0.0	0.0	-0.1	-0.1	0.0 -0.1	0.0	0.0
		l Quality	2			-0.7		0			-0.6			0.0	0:0	0:0	-0.1 -0.1	-0.1	0.0 -0.1	0.0 -0.1	0.0 -0.1
		Fue	4			-0.7		0			-0.6			0.0	0:0	0:0	0.0	-0.1	0.0 -0.1	0.0	0.0
		Press.	3			-0.7		0			-0.6			0.0	0:0	0:0	-0.1	-0.1 -0.1	0.0 -0.1	0.0	0.0
		Sylinder	2	ion		-0.7		0	ion		-0.6			0.0	0.0 ion	0.0	0.0 ion -0.1	0.0 ion -0.1	0.0 ion -0.1	0.0 -0.1 -0.2	0.0 -0.1 -0.2
		oad 0	~	Deviat		7.9		0	Deviat		6.1			0.0	0.0 Deviat	0.0 Deviat	0.0 Deviat	0.0 Deviat	0.0 Deviat 0.9	0.0 0.9 0.2	0.0 0.9 0.2
	djustment	Cylinder Le	AI	Mean	140	129	-11.0	0 5.0	Mean	116	100	-15.7		1.6	1.6	1.6	1.6	1.6	1.6	1.6	1.6
	Engine IN Process A	Auto Tuning		Pmax [Bar]	Ordered	Current	Deviation	Offset Auto/Cont.	Pcomp [Bar]	Ordered	Current	Deviation		Offset	Offset Pi [Bar]	Offset Pi [Bar]	Offset Pi [Bar] Current	Offset Pi [Bar] Current	Offset Pi [Bar] Current Offset	Offset Pi [Bar] Current Offset	Offset Pi [Bar] Current Offset

MOP Process Adjustment

0 0 48 0 Alarms		Engine >	Operation	Status	Process Information	Process Adjustment	Chief Limiters	Auxiliaries	Maintenance	Admin	Power Off () Access
Engine & Process Adjustment 2010-02-05 13:12:13	Auto Tuning Cylinder Load Cylinder Press. Fuel Quality	1 2 3 4 5 6 7 8 9 10 11 12	High Load Offset [%]		-10						

0 0 48 0	Alarms	Engine >	Operation		Status	Process Information	Process Adjustment	Chief Limiters	Auxiliaries	Maintenance	Admin	Power Off () Access
	Engine ▶ Process Adjustment 2010-02-05 13:12:32 Advice Tuning Cylinder Press. Fuel Quality	All 1 2 3 4 5 6 7 8 9 10 11 12 1	Pmax Offset [Bar]	3 -1 0 1 -1 0 -1 0 -1 0 -1	1 1 1 1 <		1.5 0.0 0.1 0.0 0.0 0.0 0.0 0.0 -		Exhaust Valve Open Timing Offset [DEG]			

0 4 27 0	Alarms		Engine >	Operation	Status	Process Information	Process Adjustment	Chief Limiters	Auxiliaries	Maintenance	Admin	Power Off () Access	
	2011-06-29 11:59:16	Fuel Quality					Suggested Fuel Quality Offset	-arcuration +11 %	Applied Fuel Quality Offset	+11%			
		ylinder Press.			Enter actual values	90 00		1					
	nt	der Load C			Reference shop test values	00.04	0.04	300.0 ZE	3				
	rocess Adjustme	ning Cylin				Lower Calorific	value [MJ/kg] Density @ 15 °C	[kg/m3]					
	Engine 🌢 Pr	Auto Tu											

() Manual I	HPS oper	ation der	nanded					Normal	ECUA_5	10116	Ξ	19:19	2 0 48 0
Engine	ef Limite	srs							2010	-02-12	10:24:3	5	Alarms
Chief Max S _F 200.0 F	PM	Engine A 200	Aax Spee										Engine >
All Chief Index I	1 	5	0	4	2	9	2	00	6	10	7	12	Status
110 100	116	2	116	110	116	110	110	110	110	1	=	110	Process Information
	1 I 1 I	1 1 1 1	1 I	1 I 1 I	1 1	1 1	1 1	1 1	1 1	1 1 1 1	1 1 1 1	1 1	Process Adjustment
Exhaust Valv	/e operat	On Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Chief Limiters
HCU status	and reset												Auxiliaries
	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Maintenance
													Admin
Chief Max Sp	eed												Power Off ①
	Current 200.0	Nev 2	0.00				••			Api	1	X	Access Chief

	0 0 48 0
Engine > Chief Limiters 2010-02-12 10:26:01	Alarms
Chief Max Speed Engine Max Speed	Engine >
200.0 RPM 200.0 RPM	Operation
All 1 2 3 4 5 6 7 8 9 10 11 12 Chief Index Limit [%]	Status
110 110 110 110 110 110 110 110	Process Information
	Process Adjustment
Exhaust Valve operation	Chief Limiters
Enabled	Auxiliaries
HCU status and reset Normal Normal	Maintenance
	Admin
Chief Index Limit - Cyl. 1	Power Off ①
Current New Apply Apply Apply X	Access Chief

MOP Cheif Limiters

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										0 0 48 0
Engine > Chief Limiters						2010	-02-12	10:26:3	μ	Alarms
Chief May Sneed Frine	May Shood									Encine P
200.0 KPM 20	NG KPM									Operation
All 1 2	3 4	2	9	7	00	6	10	7	12	Status
Chief Index Limit [%]										
110 110 110 110 - 10	110 110	110	11	11	110	110	1	110	110	Process Information
I I I I I I I I I I I I I I I I I I I I I I I I I I I I I I I I	1 1 1 1 1 1 1 1	1 1	1 I 1 I	1 1 1 1	1 1 1 1	1 1 1 1	1 1 1 1	1 1 1 1	1 I 1 I	Process Adjustment
Exhaust Valve operation										Chief Limiters
Enabled Enabled	Enabled Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Auxiliaries
HCU status and reset										
Normal	Normal Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Maintenance
										Admin
Exhaust Valve Operation - Cyl. 1										Power Off ①
Enabled	topped	WARNIN should b valve op	G! To avo e reduce: eration or	id TC sur d below 2 one cylir	ging the e 0% befor der is sto	engine los e the exhs opped.	ust		X	Access Chief

i ELFIVENV	A Fdbck	Sign. Fail	.(SIw.Dw	~				Alarm	ccu2_0	30406	ö	30:28	18 (12) 48 0
Engine > Chie	f Limit	ers							201()-03-11	08:31:0	g	Alarms
Chief Max Spi	peed	Engine N	lax Speed	-									Engine 🕨
200.0 R	Ā	200	.0 RPM										Operation
AII	-	5	~	4	2	9	7	~	6	10	7	12	Status
Chief Index L	imit [%]												
110 100	19	110	110	110	110	110	110	110	110	110	110	110	Process Information
	1 I 1 I	1 1	1 1	1 1	1 I 1 I	1 1	1 1	1 1	1 1	1 1	1 1	1 1	Process Adjustment
Exhaust Valv	e operat	ion											Chief Limiters
	Enabled	Enubled	Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Enabled	Auxiliaries
HCU status a	nd reset												
	Normal	Fault	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Maintenance
													Admin
HCU Status - C	Syl. 2												Power Off ()
	Reset											X	Access Chief



MOP Hydraulic System





MOP Hydraulic System



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2 2 48 0	Alarms		Engine	Auxiliaries >	Hydraulic System	Scavenge Air	Cylinder Lubrication	Maintenance	Admin		Power Off ()	Access Chief
10:19:19	21:27	2 Cyl.#				-~]	- S -	Stopped		X
510116	10-02-12 10:2	Cyl.	Cylinder Lub.]	Master	Stopped		
Alarm ECUA	20	Cylinder 1	Exhaust Valve Act. Booster						Closed			
					-+	-~~>-						Close (ACU-3)
					lio	7 Bar	-~~•>					Open (ACU-3)
manded	ε	s Limiter	ter Activated		Point Hyd.	07 Bar 201	-~••>			50%		
operation der	raulic Syste	Pump Torque	Ē		Set	N N	-~~•>			50%		n (ACU-
🕕 Manual HP	Auxiliaries ▶ Hyd	HPS Mode	Manual		Inlet Oil	3.0 Bar	L		ि- हि 	49%	Pump Bypass	Ope (ACU



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Plate 70329

0 (2) 27 0	Alarms		Engine	Auclisries.	Hydraulio System	Scarenge Air	Cylinder Lubrication	Maintenance	Admin			Power Off ()	Access Closef
	11:58:07	cyt.#				Ē		1					stails
	2011-06-29	0yr.2	yinder Life				we)	9 9	Running	1204-5	2.7		ă
		ylinder 1	whenest Fael C Vactore Present Act. Bommer				We)	(P)	Running	1204-4	28		
		0	(W				we:	(M) (E)	Running Folw	25%	2.8		
				1201-2 1201-3	206 206		we>	(1) (1) (1) (1) (1) (1) (1) (1) (1) (1)	Running Folw	22%	2.8		
	draulic System			yd. 08 1201-1	207 Bar 207		we)	(M)	Running Ctrl	56%	2.8		
	Auditories 9 Hyp	HPS Mode	Auto	Set Point H	207 Bar				Inlet Oil	2.8 Bar			

MOP Hydraulic System

0 0 48 0	Alarms	Engine		Auxiliaries >	Hydraulic Svstem		Scavenge Air		Cylinder Lubrication	Lubricanon	Maintenance	Admin					Power Off ①	Access	Chief
	ir 2010-02-05 13:16:11	ţ	Set Point Opening A Set Point Actual			Exhaust Receiver	Cut Out Mode	Inactive	Engine Turbine Valve	Open	Scavenge Air Receiver				Running Running Running Running			Dotaile	
	Auxiliaries IN Scavenge A		Bypass Mode	Auto					Pscav Set Point		Pscav Actual		Blowers Mode	Auto					

MOP Scavenge Air



Plate 70330





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0 0 48 0	Alarms	Engine	Auxiliaries >	Hydraulic System	Scavenge Air	Cylinder Lubrication	Maintenance	Admin		Power Off ①	Access Chief
	ir 2010-02-12 10:33:53	ţ	Set Point Opening 0% 0% Cpen Open Cpen	TC	Exhaust Receiver	Engine Calve Open	Scavenge Air Receiver Of Close Sw. Of		Stopped Stopped Stopped Close Sw. Official Close Sw		Details
	Auxiliaries > Scavenge /		Bypass Mode Auto			Pscav Set Point 2.93 Bar	Pscav Actual 8601-A 8601-B	2.69 2.69 Blowers Mode	Auto		

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Plate 70330



0 48 0	ms		ine		liaries >	raulic lem		venge	-dor	rication	tenance		in				er Off ①	ess	lef
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)-02-12	ed Rate	/kWh	10	1.00	1	1	1	1 I	1	1		1.00	0000		đ		Api	
	201(Basic Fe	1.02 g	6	1.00	1	1	1	1 I	- 1	1		1.00	00 0		₹			
		ctor	VhS%	∞	1.00	1	1	1	1 I	1	1		1 .0	0000		g			
		d Rate Fa	.34 g/kV	2	1.00	1	1	1	1 I	1	1		1.00	000		₽			◀
		Fee	د ۵	9	1.00	1	1	1	1 I	1	1		1.00	0000		₹			
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	ation	Prelube	ð	eo	1.00	1	1	1	1 I	1	1		1 .00	000		₫		M	0.34
	r Lubric		2	2	1.00	1	1	1	1 I	1	1		6 1.08	000		₫		Ne	
	Sylinder	Total	7	-	1.00	1	1	1	1 I	1	1		9. F	000		g	ctor	Current	0.34
	Auxiliaries > (Flow	47.0 l/h	Actual	Feed Rate [g/kWh]	1.4	1.2	1.0	0.6	0.4	0.2	Feed Rate	Adjust Factor	Running In	[g/kWh]	Lubricator Test Sequence	Feed Rate Fa		

0 0 48 0	Alarms	Engine	Auxiliaries	Maintenance Mainte	Invalidated Inputs	Network Status	Function Test	Trouble- shooting	Admin	Power Off () Access
	2010-02-05 13:16:51	Auxiliaries	ACU-1 ACU-2 ACU-3 SCU-1		ccu-10 ccu-11 ccu-12			ot Accessible		
		Bridge Panel	EICU-A EICU-B		ccu-e ccu-7 ccu-8 ccu-9		Engine	C Configuration B Blocked % No		
	/O Test	ECR Panel	MOP-A MOP-B		ccu-4 ccu-5	_		Controlling		
	Maintenance > System View -	ГОР	ECU-A ECU-B		ccu-1 ccu-2 ccu-3			Active This MOP		

MAN B&W

2010-02-05 13
🛕 Alarm
N/A Not available
ID Description
4001-B marker master
4002-B marker slave
4003-B quadrature master
4004-B quadrature slave
010501 Not Used
410801 EIVa.Valve
112001 Start Air Pilot Valve
011601 Lubricator Pilot Valve
0117 Cyl. Lubricator FeedBack
010801 Cylinder TDC Pulse
4107mA ElFi/FIVa Valve Control
Ch71V Test Output

Page 2 (4)

							0 0 48 0
	em View - I/O	Test		2	010-02-05 13:17	:47	Alarms
							Engine
	Signal ID	Description				>	
	4102	EIFI/FIVa Pos	sition Feedba			<	Auxiliaries
							Maintenance
			Electrical Value	Proc	ess Value		System View I/O Test
			13.1 mA)	0.0 mA		Invalidated Inputs
		24V					Network Status
30	A B C	- 🖸 🗅					Function Test
							Trouble- shooting
							Admin
Ħ	4 -	- 20 mA					
							Power Off ()
							Access
							Chief

ELFIVEINA Fd	bck Sign. Fail.(Sh	lw.Dw)	Alarm CCU	1_030406	10:37:53	1 48 1
tenance IN Sys	tem View - I/O	Test		2010-02-12 10 :3	8:51	Alarms
ž						
innel-30						Engine
No Status	Signal ID	Description			>	
	4102	ElFi/FiVa Position Feedba			<	Auxiliaries
						Maintenance
		Electrical Value	Proc	cess Value		System View I/O Test
		3.7 mA	}	0.0 mA Invalidated		Invalidated Inputs
						Network Status
J3		- 🔊 🛛				Function Test
						Trouble- shooting
annel Setup						Admin
Analog Input	4 -	- 20 mA				
						Power Off ①
						Access Chief

48 1	s		e		aries	enance	m View st	dated	ť,	ion	ing	į	r off (
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10:	:38:06													
	12 10													Ľ.
03040	10-02-			pa										
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lbck Sig	alidate	annel	Ch. No.	30										
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ELFIVE	Itenance	C	₽	ccu1										et Valid
Θ	Mair	M												ŵ.

14 48 0	arms	ngine	uxiliaries	aintenance	/stem View) Test	validated puts	etwork atus	Inction	ouble- iooting	Jmin	wer Off ① ccess
Alarm ACU2_010111 13:18:51 14	2010-02-05 13:19:01 AI	CCU 4 5 6 7 8 9 10 11 12 A B A B A B A B A B A B A B A B A B A B	Au (1) (1) (1) (1) (1) (1) (1) (1)		S X		X X X X X X X X X X X X X X X X X X X	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	5 L	4 5 6 7 8 9 10 11 12 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	evant A Reference B Cross Connection A
is from ECU B	work Status	MOP EICU ECU ACU SCU SCU <th></th> <th></th> <th></th> <th></th> <th></th> <th></th> <th>MOP EICU ACU SCU</th> <th>A B A B A B 1 2 3 1 1 2 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4</th> <th>ais MOP <u>1</u> No Reply Single Channel % Not Accessible % Not Relevent 1 No Communication 1 No Communication</th>							MOP EICU ACU SCU	A B A B A B 1 2 3 1 1 2 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	ais MOP <u>1</u> No Reply Single Channel % Not Accessible % Not Relevent 1 No Communication 1 No Communication
No Comman	Maintenance Net	Observer → Observed ↓	MOP A EICU A	ECU B	ACU 2 SCU 1	4 2 2 4	ccu 6 8	9 10 12	Cabling Map	Net Reconfigs A 485 B 495	× ok

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Admin					2010-	02-12	10:59:18		Alarms
									Engine
									Auxiliaries
									Maintenance
									Admin 🕨
UTC Date/Time 2010-02-12 10:5	012 Display	eg	Loca	al Date/Time 010-02-12	10:59:18	ĔČ	al Time		Set Time
									Version
Local Date/Time	Hours		Minutes						Power Off ①
New Date/Time 2010-02-12 10:59:14	offset -1	ź	-15	-P	+5 +15	Se	1	X	Access

MOP Set Time

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	5:53:48	Eng. No.	$\{f_{ij}\}_{i=1}^{n} := \sum_{j=1}^{n} (f_{ij})_{i=1}^{n} := \sum_{j=1}^{n} (f_{$		IMO Chief	0	0	0	16571	16761	16809	16586	17549	17305	16739	16608	16870	64941	64941	0	0	0		
	2010-11-17 1	jine Builder	(1999) (1999) (1999)		IMO Design	0	0	0	26859	26859	26859	26859	26859	26859	26859	26859	26859	51961	51961	0	0	15843		
		AO No. Eng	2232		Design	3465	3431	3837	92461	92461	92461	92461	92461	92461	92461	92461	92461	79663	79663	497	497	51872		
		Vo. IN	ats 10 25		Service	25470	25196	25234	39879	39639	39657	39868	39670	39657	39856	39699	39639	146281	147670	110627	105446	43949		
		Engine Group I	Done re-96A	heck Sums	Chief	141	141	141	746	936	984	761	1724	1480	914	783	1045	11169	11169	122	123	478		
			4.1	Parameters C	User	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
		ion	W-1008-		Type	ACU	ACU	ACU	ccu	ccu	ccu	ccu	ccu	ccu	ccu	ccu	ccu	ECU	ECU	EICU	EICU	scu		xport
	sion	ne & Versi	E-ECS-S	Init	Addr.	224	225	226	240	241	242	243	244	245	246	247	248	208	209	192	193	239		Ű
	Admin Ver	Product Nan	ME	Controller U	Q	ACU1	ACU2	ACU3	CCU1	CCU2	CCU3	CCU4	CCU5	CCUB	CCU7	CCU8	CCU9	ECUA	ECUB	EICUA	EICUB	SCU1		Refresh

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		Group N	ar-96M	ms	hief	41	41	41	46	36	84	61	24	80	14	ŝ	145	169	169	22	23	78		
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				meters C	User	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
			3-4.1	Para																				
		uo	W-1008		Type	ACU	ACU	ACU	CCU	CCU	CCU	CCU	CCU	CCU	CCU	CCU	CCU	ECU	ECU	EICU	EICU	scu		
	no	e & Versi	ECS-S	lit	Addr.	224	225	226	240	241	242	243	244	245	246	247	248	208	209	192	193	239		
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MOP Version

Page 2 (2)

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and shockwave	OK	Maintenance
		System View
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	est Test	Invalidated
		sundin
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	20.5 mA	orarius
	- 3.8 V	Function
	11.5 mA	1691
		Trouble-
	20.5 mA	Rinoolie
	7.5 mA	Admin
	-0.4V	-
		Power Off ①
vill STOP the system.	Reboot Abort Test	Access Chief

Edition 0001

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MOP Function Test

Edition 0001

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			_	sition (CH-33)	CH-34)	sor cal				value ;	put (CI	ve an			of Exh:			ode		ы.
	est	Tach	3	nger po	plifier (valve (ger sen			t mode	(CH-70)	ck on in	ist val		it mode	dic test			rmal Mo		New
	iction T		-	uel plur	iva Am	xhaust	el plun			U in tes	output (ead bai	Exhau		U in tes	top cyc			U in No	[V] 0	* 10
	e 🎙 Fur	-	 ت	Verify fi	Verify F	Verify E	Save fu	- Test		Set CCI	Adjust	Verify r	est of		Set CCI	Start/S	57.55		Set CCI	of CH-7	Curren 0.5
	itenano	HCL	ylinde					plifier	art				clic To	art		0	d test	art		value d	
	Main		Ů					An	st				S	Ste			E	st		Set	

					0 0 48 0
Maintenan	ce 🌢 Function Test	3	010-02-12 1	0:48:36	Alarms
Ĥ	U Tacho HPS				
Pre-Sta	rt Test				Engine
Start	Action/Message		Reference	Test Value	
-	Turn engine to 10 DEG before TDC at Cyl. 1		A:FF B:FF	A:FF B:FF	Auxiliaries
8	Reboot CCUs and ECUs				
	Turn engine in ahead direction to 2 DEG after TDC at Cyl. 1		A:TF B:FF		Maintenance
	Turn engine in ahead direction to 47 DEG after TDC at Cyl. 1		A:TF B:TF		System View
9	Turn engine in ahead direction to 92 DEG after TDC at Cyl. 1		A:TT B:TF		
9	Turn engine in ahead direction to 137 DEG after TDC at Cyl. 1		A:TT B:TT		Invalidated
Setting	Of Fine Adjust Parameters				endu
Start	Action/Message		Reference	Test Value	Network
	Perform PMI 0 diagram				00000
	Minimum speed required for valid measuering Delta Taoho B		=92.0 Rpm		Function
	Deita Tacho B max measured		0.96 0.96		1001
	Enter trig offset ahead and setting of EC8 parameters				Trouble- chooting
					Ruppus
Support					Admin
Details	Delta Tacho-B 0.57	Tacho Aligni	nent Deviation	-0.03	
1. Perfor	n PMI 0-digram				Power Off ①
		1P: Press Done w he PMI 0-Diagram inished.	hen Done is	Abort Test	Access Chief

								0 0 48 0
Maintenan	ce 🌢 Function Test			2	2010-02-17	09:01:56	$\left[\right]$	Alarms
Ĥ	U Tacho	SdH	_					
Pre-Sta	rt Test							Engine
start		Action/M	lessage		Reference	Test Va	alue	
	Turn engine to 10 DEG befo	re TDC at Cyl. 1			ACFF BCFF			Auxiliaries
	Reboot CCUs and ECUs							
	Turn engine in ahead direot	tion to 2 DEG after	TDC at Cyl. 1		ACTF BUFF			Maintenance >
	Turn engine in ahead direot	tion to 47 DEG afte	r TDC at Cyl. 1		ACTF BOTF			System View
	Turn engine in ahead direot	tion to 92 DEG afte	r TDC at Cyl. 1		ACTT BUTF			ILO LEST
o	Turn engine in ahead direot	tion to 187 DEG aft	ter TDC at Cyl. 1		ACTT BUTT			Invalidated
Setting	Of Fine Adjust Paramet	ters						sindur
Start		Action/M	lessage		Reference	Test Va	alue	Network
-	Perform PMI 0-diagram							oraitus
~	Minimum speed required fo	r valid measuering	g Delta Tacho B		>92.0 Rpm			Function
	Delta Tacho-B max measury	pa			-0.95 - 0.95			1001
	Enter trig offset ahead and	setting of ECS par-	ameters		i.			Trouble-
								Billioolle
Support								Admin
Details	Delta	Tacho-B	0.64	Tacho Aligni	ment Deviatio	-0.0	4	
1. Perforn	n PMI 0-digram							Power Off ()
				TIP: Press Done w the PMI 0-Diagram finished.	hen Dor	T AF	bort	Access Chief

MOP Function Test

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4 0					s		nce	'iew		P									f O	•[=
0 0 2	Alarms		Engine		Auxiliarie		Maintena	System V	1sal O	Invalidate	sındu	Network	SUBIC	Function	1691	Trouble-	Rinoolie	Admin	Power Of	Access	Chief
	-10-31 09:02:01			>	<					litedia											
	2011				Angle	86	86	8	86	88	88	86	8	88	88	8	8		8	8	Not available
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		SdH			Angle	33	88	88	33	88	8	86	88	88	88	88	86		88	88	Test OK
		_		A	Quad.	-	-		-	-	-	-	-	-	-	-	-		•	~	
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	Maintena	Ĭ	Test Det	Ta	Tar							222								2	

Edition 0001

MOP Function Test

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0 0 24 0	Alarms	Engine	Auxiliaries	Maintenance System View I/O Test	Invalidated Inputs	Network Status	Function Test	Trouble- shooting	Admin	Power Off ()	Access Chief
	2011-10-31 08:39:52	7 6 8 9 10 11 12	Exhaust Valve Position Stroke CH-34 Max Min. Stroke 10.5 mA							Fuel Plunger Exhaust Valve	Inject Return Open Close Cyclic Test
			Fuel Plunger Position CH-31 Max Min. 5 6.6 mA 0.0 mA 0			FIVA Position FB CH-30 7.6 mA	FIVA Actual Current	200			INSTRUCTION: Change MPC Mode to 'Test' to activate.
	Maintenance > Troubleshooting	Cylinder: 1 2 3	MPC Mode Normal	MPC CCU-2	→ J 34 → J 32 J 37 → J 30 →	FIVA Amplifier OK CH-20 DN	FIVA Valve Control		-dub-		Hyd. Oil ATTENTION: Stopped Engine Only!

0 2 48 0	Alarms		Engine	Auxiliaries	Maintenance Svstem View	I/O Test	Invalidated Inputs	Network Status	Function Test	Trouble- shooting	Admin	Power Off ()	Access Chief
	2010-02-26 10:13:49		10 11 12	Valve Position Max Min. Stroke	Ĩ		·····					Exhaust Valve	Open Close Cyclic Test
		_	7 8 9	Exhaust troke CH-34 18.5 m	"							Fuel Plunger	ti Inject Return
		Its HPS Events	2 6	nger Position Max Min. St				20.4 mA	Valve Control 11.5 mA				NING: Operating with uel oil pressure might age fuel booster.
		HCU Ever	3 4	Fuel Plu CH-31				CH-3C	FIVA CH-70				ig with WAF might out f rs. dam
	Troubleshooting	SdH	1	PC Mode Test	MPC CCU-	ſ	34 J70 J3						WARNING: Operatir low hydraulic press. damage accumulato
	Maintenance 🕨	нсп	Cylinder:	MF									Hyd. Oil 177 Bar

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0 2 48 0	Alarms	Engine	Auxiliaries	Maintenance	System View I/O Test	Invalidated Inputs	Network Status	Function Test	Trouble- shooting	Admin	Power Off ()	Access
	Maintenance V Troubleshooting 2010-02-26 10:16:22 A	Cylinder: 1 2 3 4 5 6 7 8 9 10 11 12 E	MPC Mode Fuel Plunger Position Exhaust Valve Position Test Max Min. Stroke CH-34 Max Min. Stroke 11.0 mA 5.2 mA 52.3 mm 5.6 mA 1 1		MPC CCU-1		FIVA Position FB	FIVA Valve Control			Fuel Plunger Exhaust Valve	Hyd. Oil WARNING: Operating with out fuel oil pressure might linject Return Open Close Cyclic Test Cyclic Test damage accumulators.

0 2 48 0	Alarms		Engine	Auxiliaries	Maintenance >	System View I/O Test	Invalidated Inputs	Network Status	Function Test	Trouble- shooting	Admin	Power Off ①	Access Chief
	2010-02-26 10:17:20 Alar	HCU Events HPS Events	3 4 5 6 7 8 9 10 11 12 Engi	Fuel Plunger Position Exhaust Valve Position Auxi CH-31 MaxMin. Stroke CH-34 MaxMin. Stroke 11.0 mA 129.1 mm	Main	Syst		CH-30 16.6 mA	FIVA Valve Control CH-70 12.0 mA Test	Trou	Adm	Fuel Plunger Exhaust Valve Pown	g with WARNING: Operating with- might out fuel oil pressure might inject Return Open Close Cyclic Test Chi s. damage fuel booster.
	nce 🕨 Troubleshooting	cu HPS	ler: 1 2 3	MPC Mode Test		WPC CC0-1	J34 J70 J30						WARNING: Operating low hydraulic press. m damage accumulators
	Maintenar	Н	Cyline										Hyd. Oil 177 B

0 2 48 0	Alarms	Engine	Auxiliaries	Maintenance	System View I/O Test	Invalidated Inputs	Network Status	Function Test	Trouble- shooting	Admin	Power Off ()	Access Chief
0	Maintenance Troubleshooting 2010-02-26 10:17:45 Ai HCU HPS HPS Events AI	Cylinder: 1 2 3 4 5 6 7 8 9 10 11 12 En	MPC Mode Fuel Plunger Position Exhaust Valve Position Au CH-31 Max Min. Stroke CH-34 Max Min. Stroke 11.0 mA				EIVA Position FB	FIVA Valve Control		Ac	Fuel Plunger Exhaust Valve Po	Hyd. Oil WARNING: Operating with out fuel oil pressure might inject Return Open Close Cyclic Test Colline Coll



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48 0					ies	ies		View		ted				-						off ()	•=
0 0	Alarms.		Engine.		Auxiliar	Auxiliari		System	System I/O Test		Invalidat Inputs		Network Status		Function Test		Trouble		Admin		Access Chief
	:03:16											1 -							10.0 [Sec]		Export
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			duence	5:39:42 (0 5:39:42 (0																	Time
		_	Sec	0-02-15 19		t						_						Ī	4.0		Zoom to Fit
		HPS Events		CCU1 201							-								2.0		Clear
		CU Events				20000		15000		10000		5	nnoc		0		-5000		0.0		Show Sequence
		H	Time	15:39:42	10:41:57	10:37:53	10:11:36	10:10:21	10:08:31	10:07:03	13:15:27	u		130	020	h31	tion Ch34				••
	eshooting	SAH	ate	-02-15	-02-12	-02-12	-02-10	-02-10	-02-10	-02-10	-02-05	descriptio	Point	dback Cl	troller Ch	osition C	alve Posi	gle Cyl. 1			
	Trouble		Ö	2010-	2010-	2010-	2010-	2010-	2010-	2010-	2010-	channel o	VA Set	VA Feed	VA Cont	Inger Po	haustva	cho Ang			
	Itenance	НСЛ	CCU	ccU1	CCU1	CCU1	CCU2	CCU1	CCU1	CCU1	CCU1	0	e FI	e FI	EIN	• Plu	e EX	• Ta	0		••
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	Alarm		Engin		Auxili		Maint	Syste		Invali	andui	Netw	nime	Funct	1691	Trout		Admi		Powe	Accer Chie
	:05:06																		8.00 [Sec]		Export
)10-02-17 09			mp ctrf failure) mp ctrf failure) mp ctrf failure) mp ctrf failure)											v	0.00		Log Manually			
	50		anence	2:30 (070119#Pu 1:21 (070119#Pu	9:38 (070119#Pu 0:01 (070119#Pu														4.00		
		_	Sec	01 11:1	09 10:2																Loom to Fit
		IPS Events		CU2 2010-02- CU2 2010-02-	CU2 2010-02- CU2 2010-02-]												0072		Clear Z All t
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		ICU Events				11	30000	30000		20000		15000		10000		2000		0.0			Seq
		Ĺ	Time	11:12:02	111115	1:10:40	1:10:01	1:09:41	11:08:56	0:58:51	0:56:58	_	Setpoint	Ch31	ŧ	n Ch34	Setpoint	ion Ch30	h70		••
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MOP Trouble Shooting