MAN Energy Solutions Future in the making



HE-C contro system standard

Introduction of MPC and Triton based control system

MAN PrimeServ

Learning objectives

Upon completion of this module you ...

- will be able to recognize the various components in the systems.
- will be able to explain the build up of the control systems.



Agenda

ME-C control system standard operation

1 ME-C engine introduction

2 Engine Control System (ECS)

- Multi Purpose Controller (MPC)
- Pneumatic system
- Triton controller

Engine type designation



Engine type designation



Main electronic and hydraulic components

Hydraulic Power Supply (HPS)

- Automatic backflush filter
- Electrical start up pumps
- Engine driven pumps

Hydraulic Cylinder Unit (HCU)

- Distribution block
- Double wall pipe (200 bar)
- FIVA / ELFI & ELVA and accumulator
- $-\mathsf{FOPB}$
- Exhaust valve actuator
- ME lubricator

Engine Control System (ECS)

– MPCs and MOP's

Crankshaft position sensing system (Tacho)

– Encoder A & B

Local Operation Panel (LOP)



Hydraulic system



Hydraulic Power Supply (HPS)



Hydraulic Cylinder Unit (HCU)



Exhaust valve and fuel oil pressure booster





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Control Network





Control Network



Network status



Network status



Network status



Multi Purpose Controller (MPC)





LED Information

The LED gives information, either as a constant light or by flashing.

- A flashing LED is a coded message from the controller. The code consists of 2 digits:
- 1. Digit is given by red flashes on yellow/orange background
- 2. Digit is given by green flashes on yellow/orange background
- The 2 digits are separated by a 1 sec. yellow/orange pulse.



| Colour | Short name | Short description |
|----------------------|---------------------|--|
| Red | ERROR | Either early initialization or fatal error |
| Orange | INIT | Initialization, no parameters available or non-normal node mode |
| Green | NORMAL | Application up and running |
| Flashing | | |
| Digits | Short name | Short description |
| (1,1) | CTRL_PRG | Onboard control programming in progress |
| (2,1) | APPLOAD_SCAN | Application download in progress – scanning for server |
| (2,2) | APPLOAD_DOWNLOAD | Application download in progress – downloading program |
| (<mark>2,3</mark>) | APPLOAD_DIP | Application download completed – reset yellow DIP switch set to ON |
| (<mark>3,1</mark>) | BOOTLOAD_SCAN | Boot loader download in progress – scanning for server |
| (3,2) | BOOTLOAD_DOWNLOAD | Boot loader download in progress – downloading program |
| (4,1) | DONGLE_VERIFY | Checking node ID dongle |
| (4, <mark>2</mark>) | DONGLE_ERROR | Dongle error – missing, broken or not programmed |
| | | |
| (<mark>4,3</mark>) | DONGLE_DIP | Node ID DIP switch not correctly reset – reset it to 0x00 |
| (4,4) | DONGLE_FORMAT | Waiting for confirmation to reformat the records in the Dongle with Start up and Persistent Data Area information. |
| (4,5) | DONGLE_DIP_CONFLICT | ID key not connected, no usable address supplied from DIP or Service Terminal. |
| (5,1) | DIP_ILLEGAL_RANGE | The selected address is outside the defined range 0xC0 – 0xFF |

Constant

(192 - 255).

Standard MPC compared with an MPC-10

MPC-10

Size: 310 x 135 x 98 mm Weight: 2.5 kg

Cabinet: 380 x 300 x 210 mm 20 external connectors

Sheltered electronics

MPC

Size: 370 x 280 x 87 mm Weight: 4.2 kg Cabinet: 500 x 400 x 210 mm 55 external connectors

Not sheltered electronics



MPC and control network summary



The Multi Purpose Controllers are identical hardware wise. They have different software configurations.

Two redundant control networks are connecting all Multi Purpose Controllers and both main operating panels computers.

A backup of the application- and setup- software is stored on both main operation panels.

At replacement, the new controller is automatically configured with correct software via the control networks.

Bridge panel and engine control room panel are wired to EICU A & B.

Local operating panel is wired to ECUA&B.

Engine Interface Control Unit (EICU)



Engine Control Unit (ECU) – Start block & checklist



Main State:

- Shows the main state of the engine FWE / Standby / At Sea
- Any warnings to the state and / or blockings will be shown here.

Start Conditions:

- Check list of conditions which must be met in order to have the engine in the corresponding state.
- One list for Finished With Engine (FWE) and one list for Standby

Auxiliary Control Unit (ACU) – Blower control



The blowers are started one by one in order to prevent overload of the electrical system.

In AUTO mode:

The blowers are started at 'Prepare Start' button.

At engine running they are controlled by the scavenge air pressure.

- stop at 0,7 bar (time delay)
- start at 0,4 bar.

At engine stop they continue to run for a default 15-20 min.

In MANUAL mode:

Operation is controlled by the operator via the MOP.

Auxiliary Control Unit (ACU) - Pump control



Electrically driven start-up pumps:

- start-up pump 1 controlled by ACU 1
- start-up pump 2 controlled by ACU 2

Engine driven pumps:

- pump 1 controlled by ACU 1
- pump 2 controlled by ACU 2
- pump 3 controlled by ACU 3
- The control is modulated, based on the pressure set point and the actual hydraulic pressure.

Engine driven pumps 4 and 5:

- same type as pump 1, 2 and 3, but they are controlled digitally by ECU's either max ahead or max astern.
- pump 4 controlled by ECU A
- pump 5 controlled by ECU B

Cylinder Control Unit (CCU)



FIVA : Fuel Injection, Valve Actuation – Proportional valve for fuel injection. – On / Off for exhaust valve operation **Control of FIVA movement** Monitor feedback from FIVA Control of Start Air Valve (SAV) Control of ME lubricator Monitor feedbacks from lubricator Monitor fuel oil booster feedback Monitor exhaust valve position feedback **One CCU per cylinder**

Cooling Water Control Unit (CWCU) – Temperature Load Dependent Cylinder Liner (LDCL)



Scavenge air Control Unit (SCU) – VTA, WHR, EGB





Main Operating Panel (MOP)



Integrated PC

MOP A:

- Touch screen
- Track ball
- Daily operation of engine

MOP B:

- Touch screen
- Keyboard with mouse
- Daily operation & trouble shooting of engine

Marine approved PC's with embedded Windows software.

Main Operating Panel (MOP)



Local Operating Panel (LOP)



MAN - ES supplied

Nabtesco supplied



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Pneumatic system for ME engine



Starting and control air systems – Slowturning



Starting and control air systems – Start/Air run



ME Tacho system



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Triton controller

Future needs of flexibility and capacity

- MPC platform has been in production since 2002.
- Key components in current platform are becoming obsolete.
- Need for higher processing power and capacity Tier III, Dual-fuel etc.







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Triton controller

| Comparison | MPC | Triton |
|--------------------|----------------------------|---------------------------------|
| Control Network | Arcnet 2Mbps shared | Ethernet 100Mbps |
| Microprocessor | Hard core | Soft core |
| Data sampling | 2kHz | 200kHz |
| Filtering | Analog | Digital |
| Display | None | Yes |
| Buttons | None | 5 |
| LED indicators | Yes, for some channels | Yes, for all channels and fuses |
| Service terminal | RS232 | USB |
| Fuses | Time lag T, non-resettable | Electronic, resettable |
| IO configuration | Fixed | Modular |
| Tacho | Separate cabling | uses Control network |
| Spare part | Controller | Module |
| Insulation monitor | External | Internal |
| Cooling | Passive | Passive |

Triton contoller



Triton contoller





Future module(s)



Engine configuration based on Triton Controller platform



MOP (Main Operation Panel)



Control Network - Ethernet Switch



Triton Controller



Monitoring signals in Triton



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Thank you very much

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