

Kongsberg Maritime Part no. 324400



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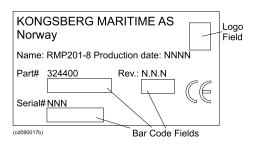
Glossary

Overview

Document user

Module identification (when contacting KM)

Figure 1 Module identification label



Module description

Function

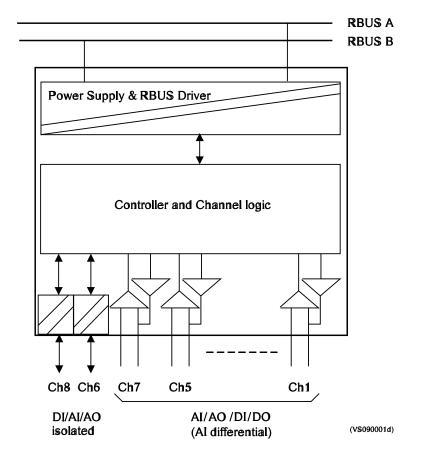


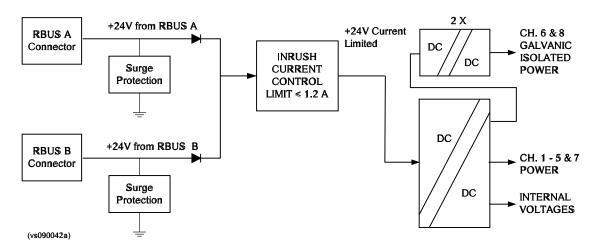
Figure 2 RMP201-8 function diagram

Power supply input

Note _

Power supplies used together with this module must have a voltage rise time at power-on that does not exceed 20 ms/V monotonic change.

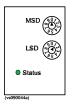




RBUS interfaces

™ RBUS A and RBUS B connector

Module address



Status LED

Table 1 Status indicators (LED) on module front

Γ	

I/O channels

HW0 HW1

HW0 HW1

Common isolated channels 1–5 and 7

Figure 4 Loop principles for channels 1–5 and 7: AI and DI

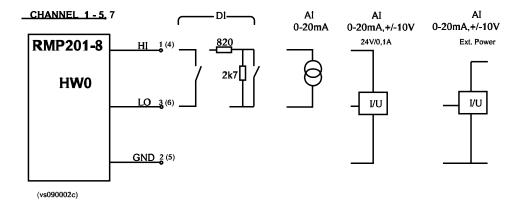


Figure 5 Loop principles for channels 1–5 and 7: AO and DO

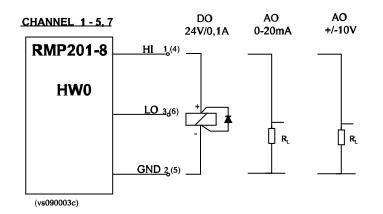
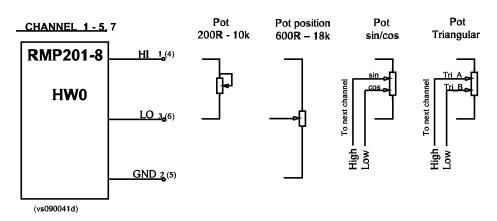
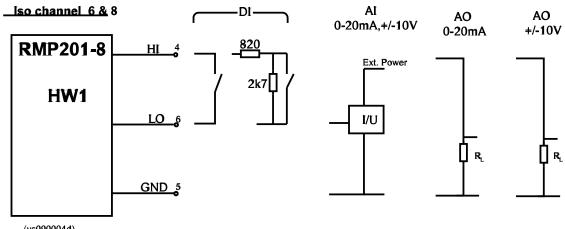


Figure 6 Loop principles for channels 1–5 and 7: Potentiometers



Individually isolated channels 6 and 8

Figure 7 Loop principles for individually isolated channels 6 and 8



(vs090004d)

Failure handling

Software controlled fail-safe

Major failure

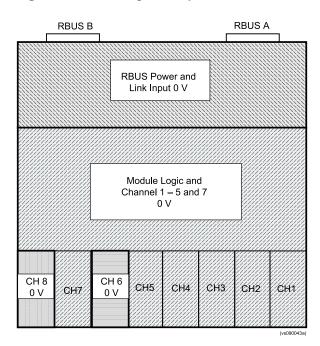
Note_____

If a serious HW error occurs in the module, all output channels are set to high impedance.

Power ON/OFF

Module power system

Figure 8 Module power systems



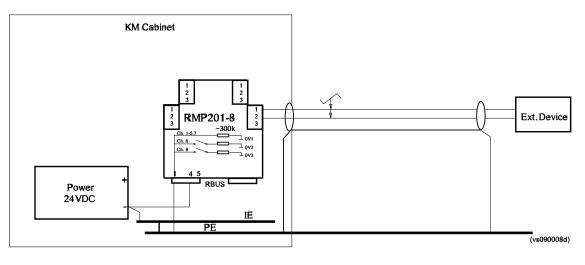
Module grounding

Note ____

In a "floating" system, current will flow through all parasitic capacitors (Cp) if there is a potential difference, also known as common mode voltage. There are no practical ways to get rid of the Cps, so the best solution is to reduce the common mode voltage by grounding, or reduce the influence by proper shielding. In order to avoid noise, the best way is to use a common ground together with proper shielding.

Floating external device, cable grounded at both ends

Figure 9 Floating external device, cable grounded at both ends

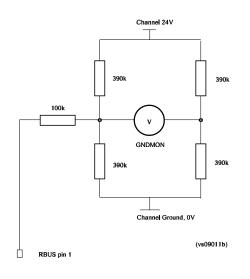


Note _

RMP201–8 ground monitoring has to be configured off, if interfaced field side equipment is implemented with ground monitoring functionality.

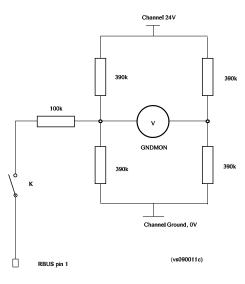
Monitored ground





Floating ground isolation

Figure 11 Floating ground circuit diagram



Note _

The default setting of the switch K is 'off'.

Self diagnostics

Module identification code

Fail-safe

Status shown on front LED Status LED

I/O loop status

Internal circuitry tests

Running diagnostics

Calibration

±

Temperature

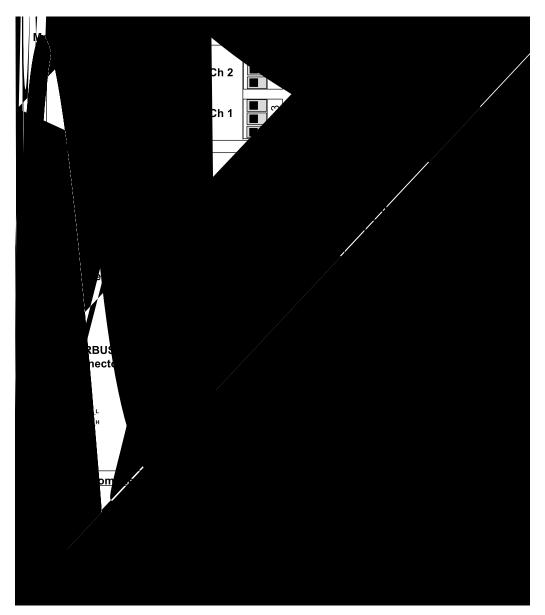
Technical specifications

1

	1
L	1

Configuration

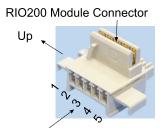
Figure 12 Layout of the RMP201-8



RBUS A and RBUS B connector

тм





RBUS T-BUS Connector (cd090009b)

Table 2 RBUS A and RBUS B connector terminal allocation

X1 to X4 terminal rows

тм

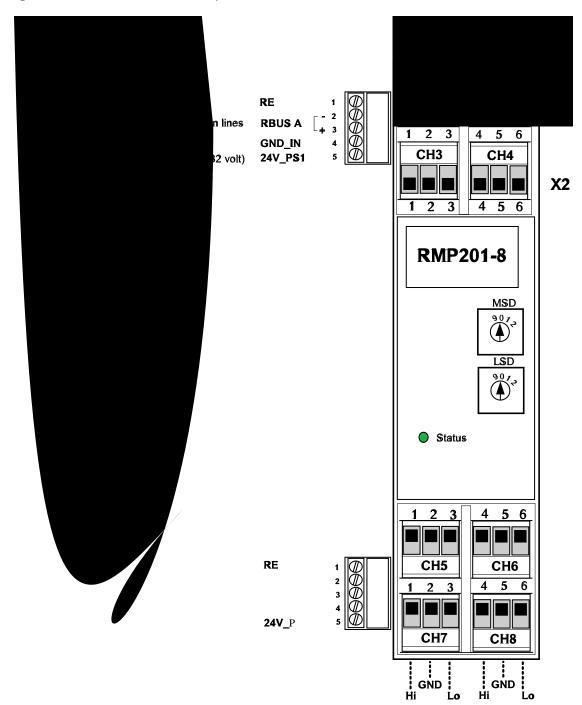


Figure 14 X1 to X4 terminal layout

Table 3 X1 and X2 terminal rows terminal allocation

Note _____

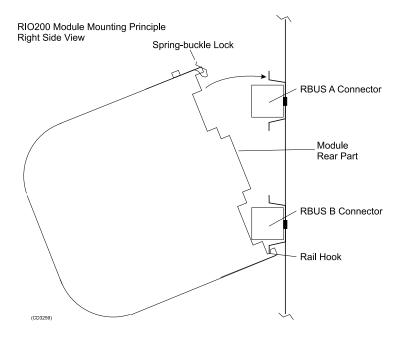
Channel 6 and 8 in the following list are the two individually galvanic isolated channels.

Table 4 X3 and X4 terminal rows terminal allocation

Installation

Caution _

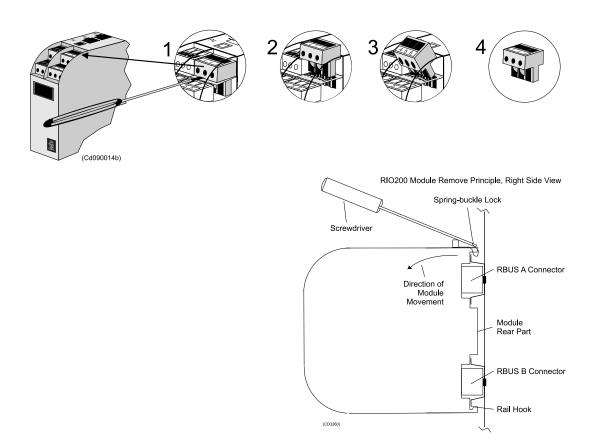
The module can be unpacked and handled without ESD protection, but electrostatic discharge can damage components on the module when terminating wires and cables to it. Therefore always wear a correctly-connected earthing strap when working on the module.

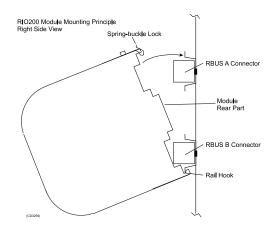


Replacement

Caution _

The module can be unpacked and handled without ESD protection, but electrostatic discharge can damage components on the module when terminating wires and cables to it. Therefore always wear a correctly-connected earthing strap when working on the module.





Note _

The terminal block headers are coded so there is only one way to enter all four headers on one side of the module.

